

Quantum Physics: Fields, Particles and Information Geometry

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In honour of A. P. Balachandran, on the occasion of his 80th birthday.

**Nonassociative differential geometry and gravity
with non-geometric fluxes**

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Why nonassociative gravity?

Geometry of fluxes

Example: electron in a strong magnetic field B . In this regime, due to the minimal coupling with the background gauge field, the dynamics takes place in a reduced phase space. It coincides with the electron coordinates thus the electron coordinates become noncommutative: $[x, y] = \frac{i\hbar}{B}$.

Similarly open strings endpoints test a noncommutative space (brane) in the presence of a nonvanishing constant B -field flux.

Yang-Mills theory captures the low energy effective D -brane action. In the presence of a B -field this suggested a description in terms of Noncommutative Yang-Mills theory: YM-theory on the *nongeometric background* $[x, y] = i\theta$.

The study of Yang-Mills (and Born-Infeld) theories in these noncommutative spaces has proven very fruitful.

-it provides an exact low energy D -brane effective action (in a given $\alpha' \rightarrow 0$ sector of string theory where closed strings decouple).

-it allows to realize string theory T-duality symmetry within the low energy physics of Noncommutative (Super) Yang-Mills theories [Connes, Douglas, Schwartz 1997].

Key example: NC-torus

NC plane $[x^i, x^j] = \theta^{ij} \Rightarrow$ NC torus coordinates $U^i = e^{ix^i}$.

NCSYM: $U(n), \theta^{ij}, G_{ij}, g_{SYM}, M$ first Chern number $\frac{1}{2\pi} \int \text{Tr} F$.

NCSYM': $U(n'), \theta'^{ij}, G'_{ij}, g'_{SYM}, M'$.

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Let $\Lambda = \begin{pmatrix} \mathcal{A} & \mathcal{B} \\ \mathcal{C} & \mathcal{D} \end{pmatrix} \in SO(d, d, Z)$, then

$$\theta' = (\mathcal{A}\theta + \mathcal{B})(\mathcal{C}\theta + \mathcal{D})^{-1},$$

$$G'^{ij} = (\mathcal{C}\theta + \mathcal{D})^i_k (\mathcal{C}\theta + \mathcal{D})^j_l G^{kl},$$

$$g'^2_{SYM} = \sqrt{|\det(\mathcal{C}\theta + \mathcal{D})|} g^2_{SYM},$$

$$\begin{pmatrix} n' \\ M' \end{pmatrix} = S(\Lambda) \begin{pmatrix} n \\ M \end{pmatrix} \quad \text{spinor representation } S(\Lambda)$$

The rank and the bundle topology of the NCSYM theory determine the D0 and D2 brane charges in IIA string theory. Noncommutativity θ^{ij} captures the presence of nontrivial NS B field. The action of these $SO(d, d, Z)$ rotations matches the T-duality transformation on metric, string coupling constant, D-brane charges, NS field of type IIA string theory.

Closed Strings

T -dualities for closed strings on \mathbb{T}^d in the presence of a constant 3-form H -flux suggest the following chain of fluxes:

$$H_{abc} \xrightarrow{T_a} f^a{}_{bc} \xrightarrow{T_b} Q^{ab}{}_c \xrightarrow{T_c} R^{abc}$$

- H and f -fluxes on Riemannian manifolds,
- Q -flux on T-fold (global description involves T-duality transformations as transition functions between local trivializations of tangent bundle);
- R -flux *non geometric background*. Expected global description in terms of noncommutative and nonassociative structures

[Lüst, Blumenhagen, et al; Mylonas, Schupp, Szabo]

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In R -flux background closed strings are expected to probe the phase space

$$[x^\mu, x^\nu] = \frac{i\ell_s^3}{3\hbar} R^{\mu\nu\rho} p_\rho, \quad [x^\mu, p_\nu] = i\hbar \delta^\mu{}_\nu \quad \text{and} \quad [p_\mu, p_\nu] = 0,$$

with spacetime nonassociativity:

$$[x^\mu, x^\nu, x^\rho] := [x^\mu, [x^\nu, x^\rho]] + [x^\nu, [x^\rho, x^\mu]] + [x^\rho, [x^\mu, x^\nu]] = \ell_s^3 R^{\mu\nu\rho}.$$

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Low energy effective action for closed strings includes the gravitational action.

- Nonassociative Gravity as low energy action in the presence of R -flux?
- T-duality transformations act within nonassociative GR?

This motivates the study of:

- A gravity theory on the phase space \mathcal{M} of coordinates $X^A = (x^\mu, p_\nu)$.
- The induced Einstein vacuum equations on the nonassociative spacetime of the coordinates x^μ .

[P.A, Dimitrijevic, Szabo, arXiv:1710.11467]

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A key observation is that the nonassociative R-flux phase space can be obtained via Drinfeld 2-cochain twist deformation of commutative phase space.

- This work is then a nontrivial nonassociative generalization of the NC differential geometry and *Riemannian geometry* constructed in [Wess Group].
- For an earlier study toward this goal see [Blumenhagen, Fuchs].
- This work is also an explicit (and self contained) example of NA differential geometry as developed for arbitrary 2-cochain twist in [Barnes, Schenkel, Szabo].

Drinfeld twist

Let Ξ be the Lie algebra of vector fields on phase space \mathcal{M} . Let $U\Xi$ be the universal enveloping algebra (of sums of products of vector fields). It is a Hopf algebra, i.e. a **symmetry algebra**, with, for all $u \in \Xi$,

$$\Delta(u) = u \otimes 1 + 1 \otimes u, \quad \varepsilon(u) = 0, \quad S(u) = -u$$

Consider the twist [Mylonas, Schupp, Szabo]

$$\mathcal{F} = \exp \left(-\frac{i\hbar}{2} (\partial_\mu \otimes \tilde{\partial}^\mu - \tilde{\partial}^\mu \otimes \partial_\mu) - \frac{i\ell_s^3}{12\hbar} R^{\mu\nu\rho} (p_\nu \partial_\rho \otimes \partial_\mu - \partial_\mu \otimes p_\nu \partial_\rho) \right)$$

built with the vector fields $\partial_A = \left(\frac{\partial}{\partial x^\mu} = \partial_\mu, \frac{\partial}{\partial p_\mu} = \tilde{\partial}^\mu \right)$ and the R-flux.

The Hopf algebra $U\Xi$ is twist deformed in the quasi-Hopf algebra $U\Xi^{\mathcal{F}}$ with same product, ε and S of $U\Xi$, but new coproduct, for all $\xi \in U\Xi$,

$$\Delta_{\mathcal{F}}(\xi) = \mathcal{F}\Delta(\xi)\mathcal{F}^{-1}$$

in particular $\Delta_{\mathcal{F}}(\partial_{\mu}) = 1 \otimes \partial_{\mu} + \partial_{\mu} \otimes 1$ and

$$\Delta_{\mathcal{F}}(\tilde{\partial}^{\mu}) = 1 \otimes \tilde{\partial}^{\mu} + \tilde{\partial}^{\mu} \otimes 1 + i\kappa R^{\mu\nu\rho} \partial_{\nu} \otimes \partial_{\rho}, \quad \kappa \equiv \ell_s^3/6\hbar$$

$U\Xi^{\mathcal{F}}$ is a quasi-Hopf algebra because while $(\Delta \otimes id)\Delta = (id \otimes \Delta)\Delta$, for $\Delta_{\mathcal{F}}$ we have

$$\Phi (\Delta_{\mathcal{F}} \otimes id) \Delta_{\mathcal{F}}(\xi) = (id \otimes \Delta_{\mathcal{F}}) \Delta_{\mathcal{F}}(\xi) \Phi$$

where the associator Φ is given by

$$\Phi = \exp\left(\frac{\ell_s^3}{6} R^{\mu\nu\rho} \partial_{\mu} \otimes \partial_{\nu} \otimes \partial_{\rho}\right) =: \phi_1 \otimes \phi_2 \otimes \phi_3$$

Gravity is based on general covariance under infinitesimal diffeomorphisms, i.e. under the Lie algebra of vector fields (equivalently $U\Xi$). We construct a NC/NA Riemannian geometry covariant under the quasi Hopf algebra $U\Xi^{\mathcal{F}}$.

Key point:

Consider commutative algebras that carry a representation of $U\Xi$; deform these algebras so that they carry a representation of $U\Xi^{\mathcal{F}}$.

Example: Algebra of functions $\longrightarrow A_{\star} \equiv$ NC/NA algebra of functions.

Notation: $\mathcal{F} = \bar{f}^{\alpha} \otimes \bar{f}_{\alpha}$

$$f \star g = \bar{f}^{\alpha}(f) \cdot \bar{f}_{\alpha}(g)$$

NC controlled by the \mathcal{R} -matrix $\mathcal{R} = \mathcal{F}^{-2}$,

$$f \star g := \bar{R}^{\alpha}(g) \star \bar{R}_{\alpha}(f) =: {}^{\alpha}g \star_{\alpha} f .$$

NA controlled by the associator Φ ,

$$(f \star g) \star h = \phi_1 f \star (\phi_2 g \star \phi_3 h) .$$

$U\Xi^{\mathcal{F}}$ -**covariance** of \star -product: let $\Delta_{\mathcal{F}}(\xi) = \xi_{(1)} \otimes \xi_{(2)}$ then

$$\xi(f \star g) = \xi_{(1)} f \star \xi_{(2)} g$$

This \star -product on coordinates functions gives the R -flux algebra:

$$[x^{\mu}, x^{\nu}]_{\star} = 2i\kappa R^{\mu\nu\rho} p_{\rho} , \quad [x^{\mu}, p_{\nu}]_{\star} = i\hbar \delta^{\mu}_{\nu} \quad \text{and} \quad [p_{\mu}, p_{\nu}]_{\star} = 0$$

Tensor algebra \mathcal{T}_\star

$$\tau \otimes_\star \tau' = \bar{f}^\alpha(\tau) \otimes \bar{f}_\alpha(\tau'),$$

Exterior algebra Ω_\star^\bullet

$$\theta \wedge_\star \theta' = \bar{f}^\alpha(\theta) \wedge \bar{f}_\alpha(\theta').$$

In particular we have the A_\star -bimodules of forms Ω_\star and of vector fields Ξ_\star .

$$f \star d\tilde{x}_\mu = f \cdot d\tilde{x}_\mu = d\tilde{x}_\mu \star f ,$$

$$f \star dx^\mu = f \cdot dx^\mu - \frac{i\kappa}{2} R^{\mu\nu\rho} (\partial_\nu f) \cdot d\tilde{x}_\rho = dx^\mu \star f - d\tilde{x}_\rho \star i\kappa R^{\mu\nu\rho} (\partial_\nu f)$$

$$f \star \partial_\mu = f \cdot \partial_\mu = \partial_\mu \star f ,$$

$$f \star \tilde{\partial}^\mu = f \cdot \tilde{\partial}^\mu + \frac{i\kappa}{2} R^{\mu\nu\rho} (\partial_\nu f) \cdot \partial_\rho = \tilde{\partial}^\mu \star f + \partial_\rho \star i\kappa R^{\mu\nu\rho} (\partial_\nu f)$$

Pairing between forms and vectors $\langle , \rangle : \Omega \times \Xi \rightarrow C^\infty(\mathcal{M})$ is deformed to

$$\langle , \rangle_\star := \langle , \rangle \circ \mathcal{F}^{-1} : \Omega_\star \times \Xi_\star \rightarrow A_\star , \quad (1)$$

explicitly

$$\langle \omega , u \rangle_\star = \langle \bar{f}^\alpha(\omega) , \bar{f}_\alpha(u) \rangle . \quad (2) \quad \boxed{\text{pai}}$$

Covariance under $U \Xi^{\mathcal{F}}$: $\xi \langle \omega , u \rangle_\star = \langle \xi^{(1)}\omega , \xi^{(2)}u \rangle_\star .$

The pairing generalizes to

$$\langle , \rangle_\star : \Omega_\star \wedge_\star \Omega_\star \times \Xi \wedge_\star \Xi \rightarrow A_\star .$$

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The pairing generalizes to

$$\langle , \rangle_\star : \Omega_\star \wedge_\star \Omega_\star \times \Xi \wedge_\star \Xi \rightarrow A_\star .$$

Notice that $\langle \omega , \rangle_\star$ is a right A_\star -linear map $\Xi_\star \rightarrow A_\star$. More in general we consider right A_\star -linear maps between A_\star -bimodules

$$L : V_\star \rightarrow W_\star$$

(e.g. V_\star, W_\star star-tensor products of Ω_\star and Ξ_\star).

Action of $U \Xi^{\mathcal{F}}$ on $L : V_\star \rightarrow W_\star$ is the **adjoint** action:

$$\xi L(v) := (\xi L)(v) = \xi^{(1)}(L(S(\xi^{(2)})v))$$

so that we have **covariance**: $\xi(L(v)) = \xi^{(1)}L(\xi^{(2)}v).$

Composition of two right A_\star -linear maps is defined by

$$L_1 \bullet L_2 := \phi_1 L_1 \circ \phi_2 L_2 \circ \phi_3$$

so that we have **covariance**: $\xi(L_1 \bullet L_2) = \xi^{(1)} L_1 \bullet \xi^{(2)} L_2$
moreover $L_1 \bullet L_2$ is again right A_\star -linear.

Summary: we defined $\star, \otimes_\star, \wedge_\star, \langle , \rangle_\star, \bullet$. They are invariant under $U \equiv \mathcal{F}$.

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Summary: we defined $\star, \otimes_\star, \wedge_\star, \langle, \rangle_\star, \bullet$. They are invariant under $U \equiv \mathcal{F}$.

More differential geometry:

Connection

A connection is a linear map

$$\begin{aligned} \nabla^\star : \Xi_\star &\longrightarrow \Xi_\star \otimes_\star \Omega_\star \\ u &\longmapsto \nabla^\star u = u^i \otimes_\star \omega_i, \end{aligned}$$

where $u^i \otimes_\star \omega_i \in \Xi_\star \otimes_\star \Omega_\star$, which satisfies the right Leibniz rule

$$\nabla^\star(u \star f) = (\bar{\phi}_1 \nabla^\star(\bar{\phi}_2 u)) \star \bar{\phi}_3 f + u \otimes_\star df$$

Coefficients of the connection along a vector field ∂_A : $\nabla_{\partial_A}^\star \partial_B = \partial_C \star \Gamma_{BA}^C$.

∇^* uniquely lifts to a connection

$$d_{\nabla^*} : \Xi_{\star} \otimes_{\star} \Omega_{\star}^{\bullet} \longrightarrow \Xi_{\star} \otimes_{\star} \Omega_{\star}^{\bullet} .$$

Theorem

$$T^*(u, v) = \phi_1 \nabla_{\phi_2 v}^* \phi_3 u - \phi_1 \nabla_{\phi_2 \alpha u}^* \phi_3 v + [u, v]_{\star}$$

(5) Tor

Proof: True for $u = \partial_A, v = \partial_B$. Then show that T^* is well defined and right A_{\star} -linear.

Curvature

$$R^* = d_{\nabla}^* \bullet d_{\nabla}^* : \Xi_{\star} \longrightarrow \Xi_{\star} \otimes_{\star} \Omega_{\star}^2 .$$

Is indeed right A_{\star} -linear (hence a tensor).

Define curvature as a map $R^* : \Xi_{\star} \otimes_{\star} (\Xi_{\star} \wedge_{\star} \Xi_{\star}) \longrightarrow \Xi_{\star}$ giving on vector fields $u, v, z \in \Xi_{\star}$ the vector field

$$R^*(z, u, v) = \langle \bar{\phi}_1 R^* \bar{\phi}_2 z, \bar{\phi}_3 (u \wedge_{\star} v) \rangle_{\star} .$$

Theorem

$$R^*(z, u, v) = \kappa_1 \check{\phi}_1 \phi'_1 \nabla_{\bar{\rho}_3 \bar{\zeta}_3 \bar{\phi}_3 \phi'_{3v}}^* \left(\bar{\rho}_1 \bar{\phi}_1 \kappa_2 \check{\phi}_2 \phi'_2 \nabla_{\bar{\rho}_2 \bar{\zeta}_2 \check{\phi}_3 u}^* \bar{\zeta}_1 \bar{\phi}_2 \kappa_3 z \right) - \kappa_1 \check{\phi}_1 \phi'_1 \nabla_{\bar{\rho}_3 \bar{\zeta}_3 \bar{\phi}_3 \phi'_{3\alpha u}}^* \left(\bar{\rho}_1 \bar{\phi}_1 \kappa_2 \check{\phi}_2 \phi'_2 \nabla_{\bar{\rho}_2 \bar{\zeta}_2 \check{\phi}_3 \alpha v}^* \bar{\zeta}_1 \bar{\phi}_2 \kappa_3 z \right) + \nabla_{[u,v]_{\star}}^* z$$

where

$$\nabla_v^* u := \langle \bar{\phi}_1 \nabla^* \bar{\phi}_2 u, \bar{\phi}_3 v \rangle_{\star}$$

Proof: as for torsion.

Ricci tensor

$$\text{Ric}^*(u, v) = \langle dx^A, R^*(u, \partial_A, v) \rangle_\star .$$

Riemannian Geometry

Metric tensor: $g^\star = g_{MN} \star dx^M \otimes_\star dx^N$.

Theorem

There exists one and only one torsion free and metric compatible connection.

It is determined by $g_{MN} \star dx^M \star \Gamma_{AD}^N = \frac{1}{2} (\partial_D g_{AB} + \partial_A g_{BD} - \partial_B g_{AD}) \star dx^B$.

Einstein vacuum equations:

$$\text{Ric}^\star = 0 .$$

We can pull back these equation on spacetime (spanned by x^μ coordinates only). Considering momentum space with the flat metric $\eta^{\mu\nu}$ we obtain Ricci tensor $\text{Ric}^\circ_{\mu\nu}$ on the zero momentum leaf and spacetime Einstein equations

$$\text{Ric}^\circ_{\mu\nu} = 0$$

Up to first order in R-flux (but second order in the twist deformation) we explicitly have

$$\begin{aligned} \text{Ric}^\circ_{\mu\nu} = \text{Ric}_{\mu\nu} + \frac{\ell_s^3}{12} R^{\alpha\beta\gamma} & \left(\partial_\rho (\partial_\alpha \mathbf{g}^{\rho\sigma} (\partial_\beta \mathbf{g}_{\sigma\tau}) \partial_\gamma \Gamma_{\mu\nu}^\tau) - \partial_\nu (\partial_\alpha \mathbf{g}^{\rho\sigma} (\partial_\beta \mathbf{g}_{\sigma\tau}) \partial_\gamma \Gamma_{\mu\rho}^\tau) \right. \\ & + \partial_\gamma \mathbf{g}_{\tau\omega} (\partial_\alpha (\mathbf{g}^{\sigma\tau} \Gamma_{\sigma\nu}^\rho) \partial_\beta \Gamma_{\mu\rho}^\omega - \partial_\alpha (\mathbf{g}^{\sigma\tau} \Gamma_{\sigma\rho}^\rho) \partial_\beta \Gamma_{\mu\nu}^\omega \\ & + (\Gamma_{\mu\rho}^\sigma \partial_\alpha \mathbf{g}^{\rho\tau} - \partial_\alpha \Gamma_{\mu\rho}^\sigma \mathbf{g}^{\rho\tau}) \partial_\beta \Gamma_{\sigma\nu}^\omega \\ & \left. - (\Gamma_{\mu\nu}^\sigma \partial_\alpha \mathbf{g}^{\rho\tau} - \partial_\alpha \Gamma_{\mu\nu}^\sigma \mathbf{g}^{\rho\tau}) \partial_\beta \Gamma_{\sigma\rho}^\omega \right) \end{aligned}$$

Riemannian Geometry

Levi Civita connection determined by

$$d\langle g^*, (\partial_A \otimes_{\star} \partial_B) \rangle_{\star} = \langle g^*, \nabla^{\star}(\partial_A \otimes_{\star} \partial_B) \rangle_{\star}$$

proceed as in classical case (use symmetry of g_{AB} and torsion free condition) to obtain:

$$g_{MN} \star dx^M \star \Gamma_{AD}^N = \frac{1}{2} (\partial_D g_{AB} + \partial_A g_{BD} - \partial_B g_{AD}) \star dx^B .$$

i.e.

$$dx^M \star G_{MN} \star \Gamma_{AD}^N = dx^M \star \frac{1}{2} \left(\partial_D g_{AM} + \partial_A g_{MD} - \partial_M g_{AD} + i\kappa \mathcal{R}^{EF}{}_M (\partial_E \partial_D g_{AF} + \partial_E \partial_A g_{DF}) \right) ,$$

with

$$G_{MN} = g_{MN} + i\kappa \mathcal{R}^{EF}{}_M \partial_E g_{NF} ,$$

Invert G_{MN} as a differential operator and obtain a unique solution for the Levi Civita connection.

This gives Einstein equations in vacuum on \mathcal{M} phase space.