# How to prove the 3D forward solver? 2D vs. 3D responses

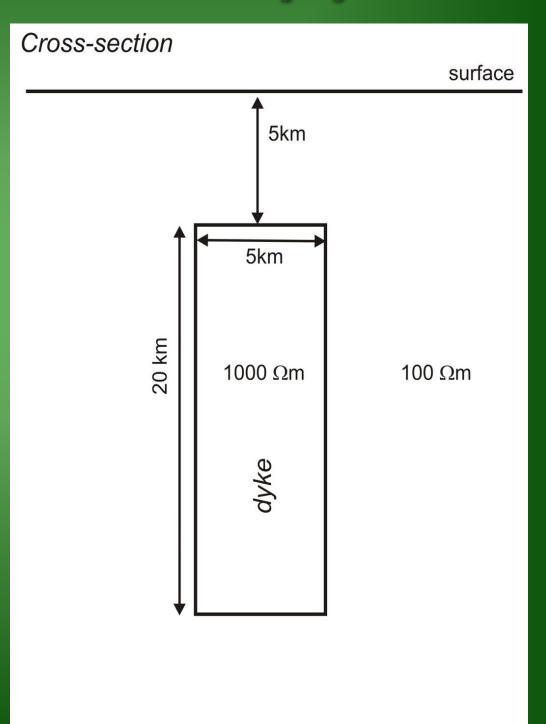
Marion Miensopust, DIAS

## The first approach

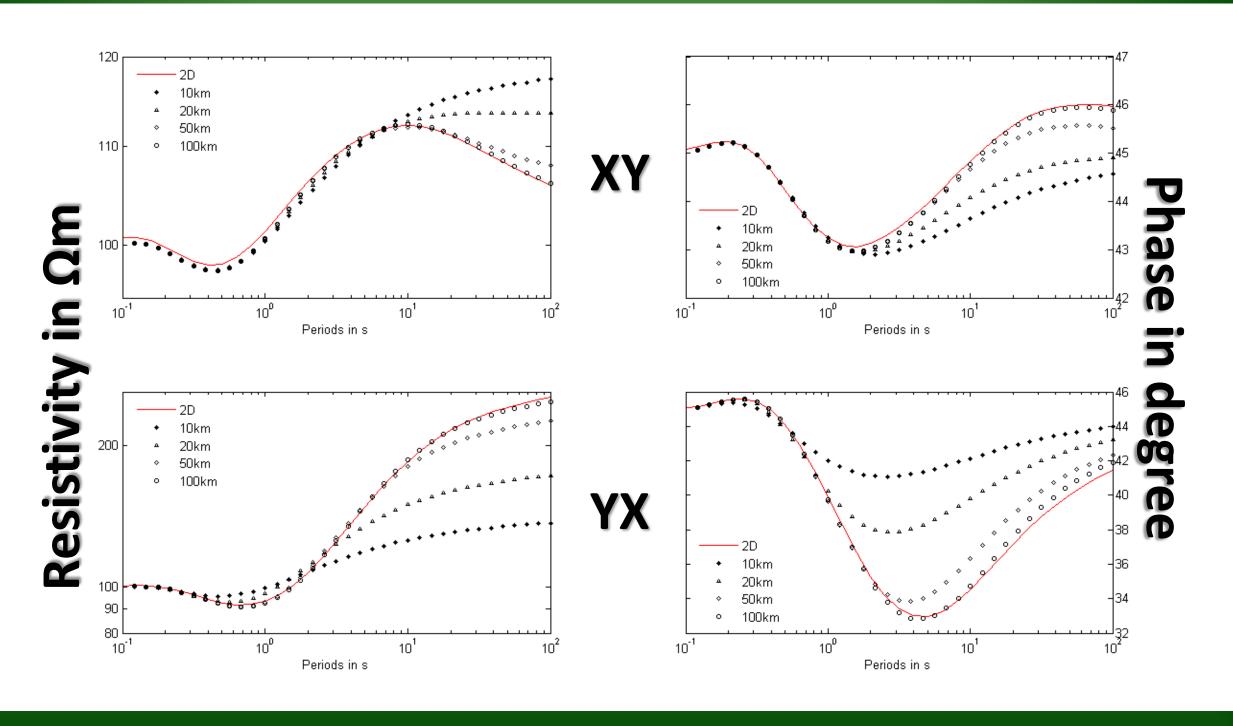
2D model: 1000  $\Omega$ m dyke in 100  $\Omega$ m surrounding; 5 km wide and 20 km thick

3D model: same dyke structure but with different length

Idea: with increasing length approach of 3D responses to the 2D model



# Example sounding curves



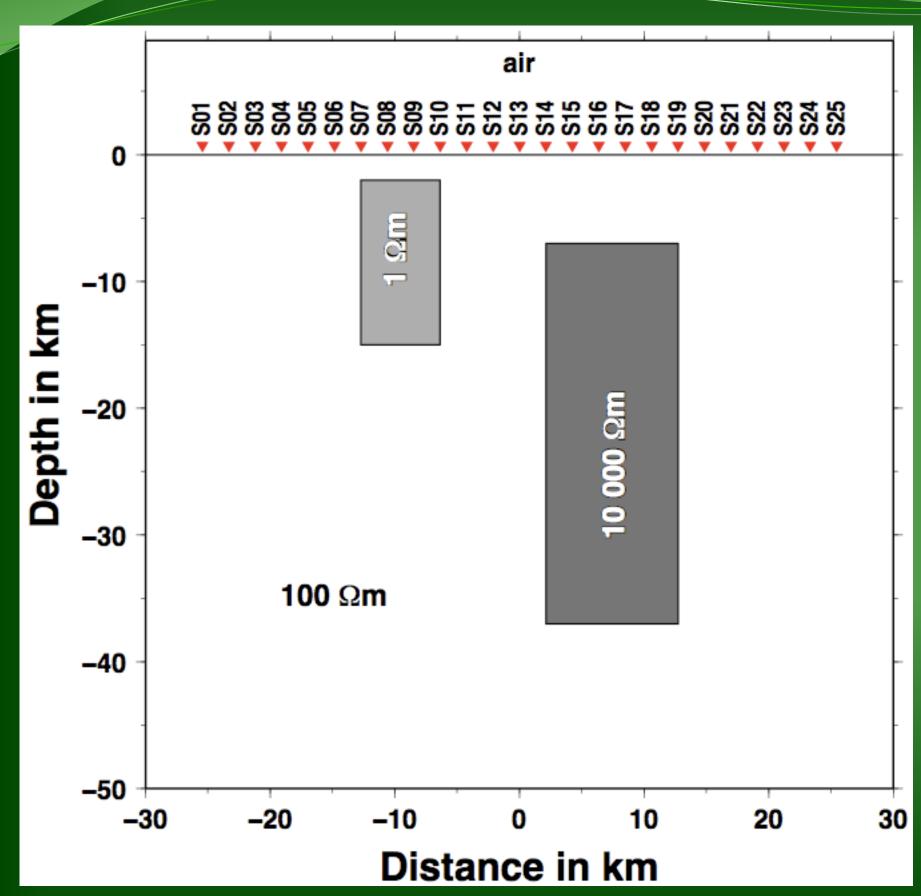
## The problem

# This test ONLY addresses the off-diagonal elements!!!

### The second approach

2D modeling of real data -> rotate perpendicular to strike (minimize the diagonal elements)

testing the diagonal elements of the 3D solver do it the other way round



#### 2D model

2 dykes
with N-S
strike
direction

profile orientation W-E

# Rotation of the coordinate system

$$\mathbf{Z}_{2Drot} = \mathbf{R}\mathbf{Z}_{2D}\mathbf{R}'$$

$$\mathbf{R} = \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix}$$

dyke: N-S

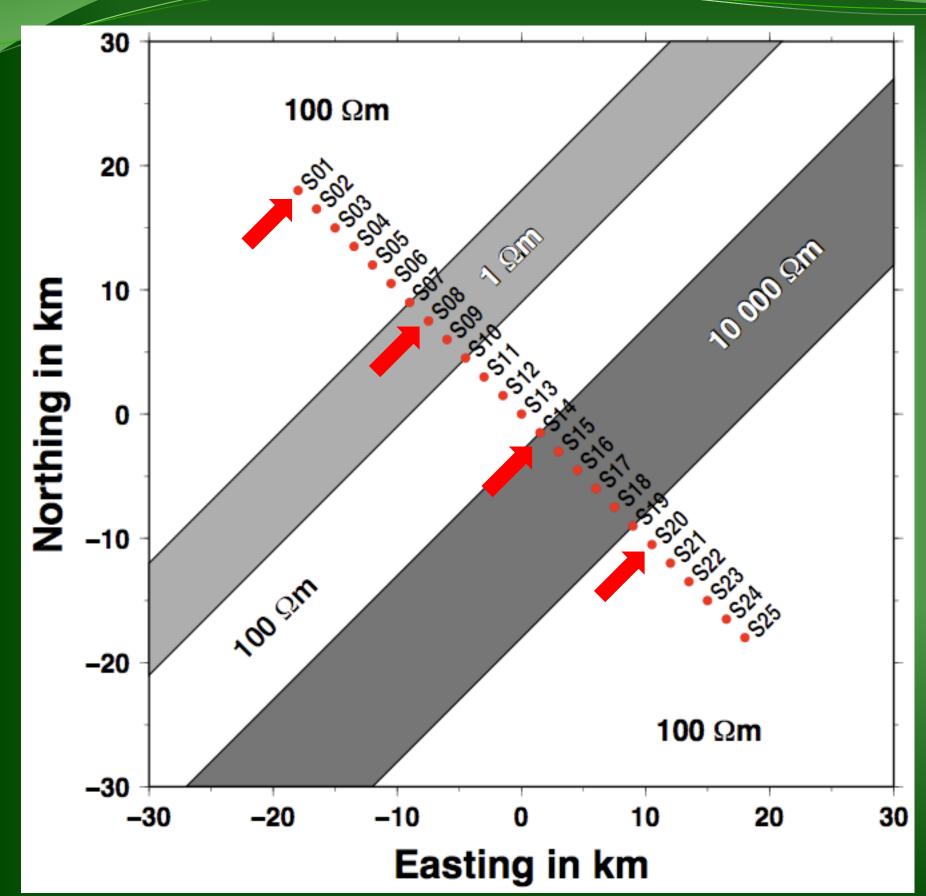
profile: W-E

-45 degrees

rotated 2D

dyke: NE-SW

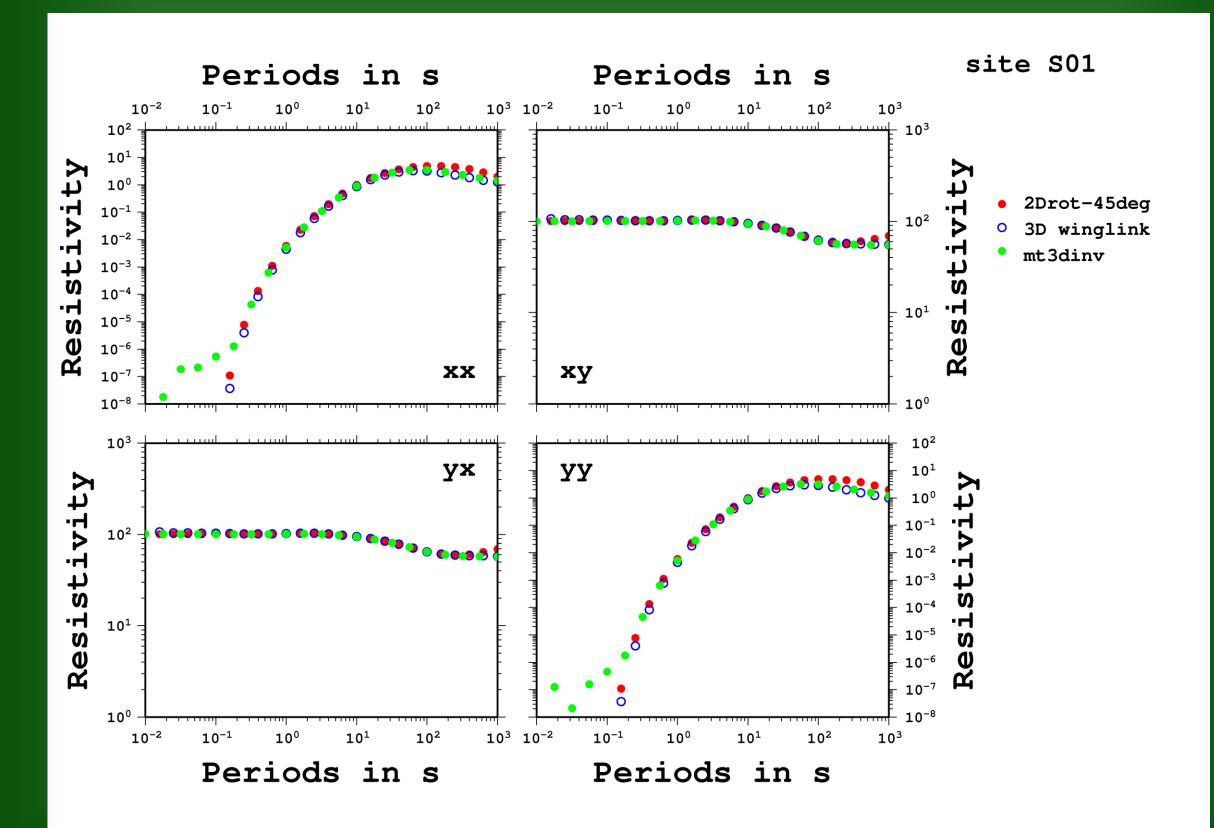
profile: NW-SE

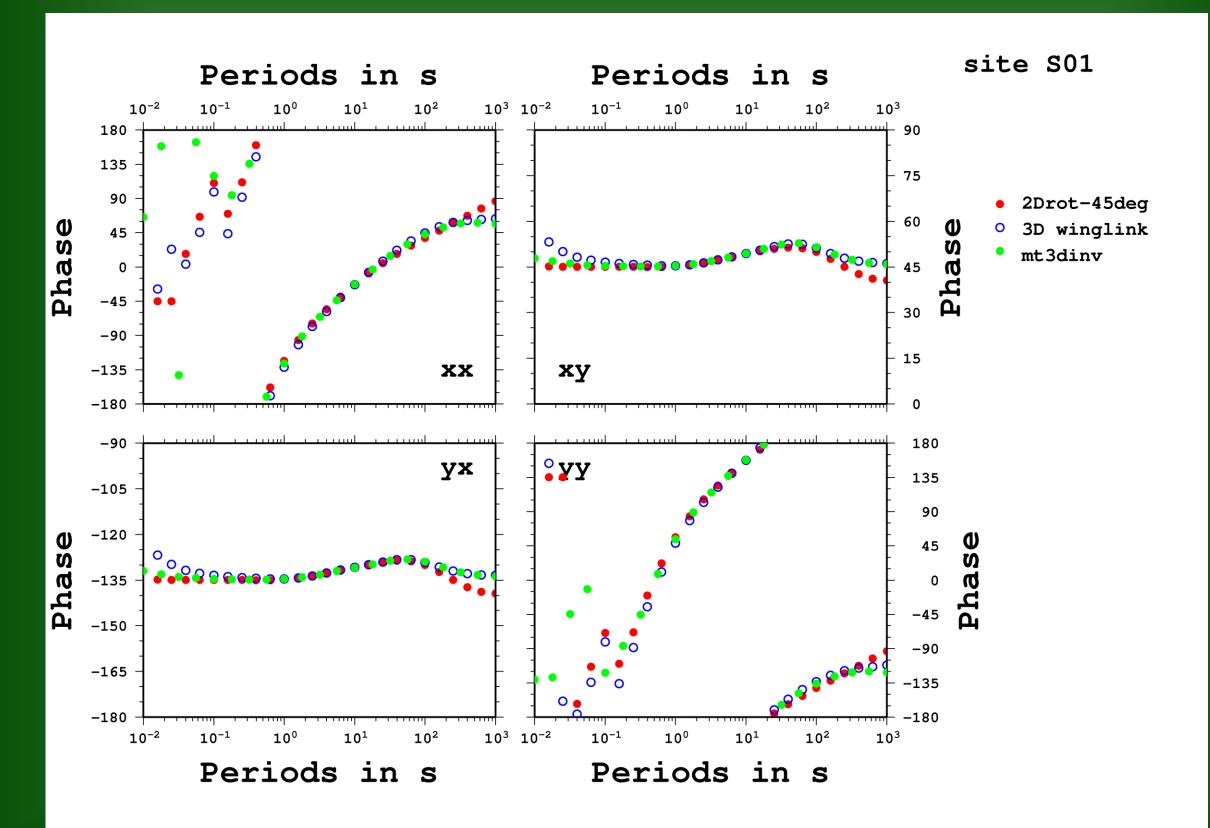


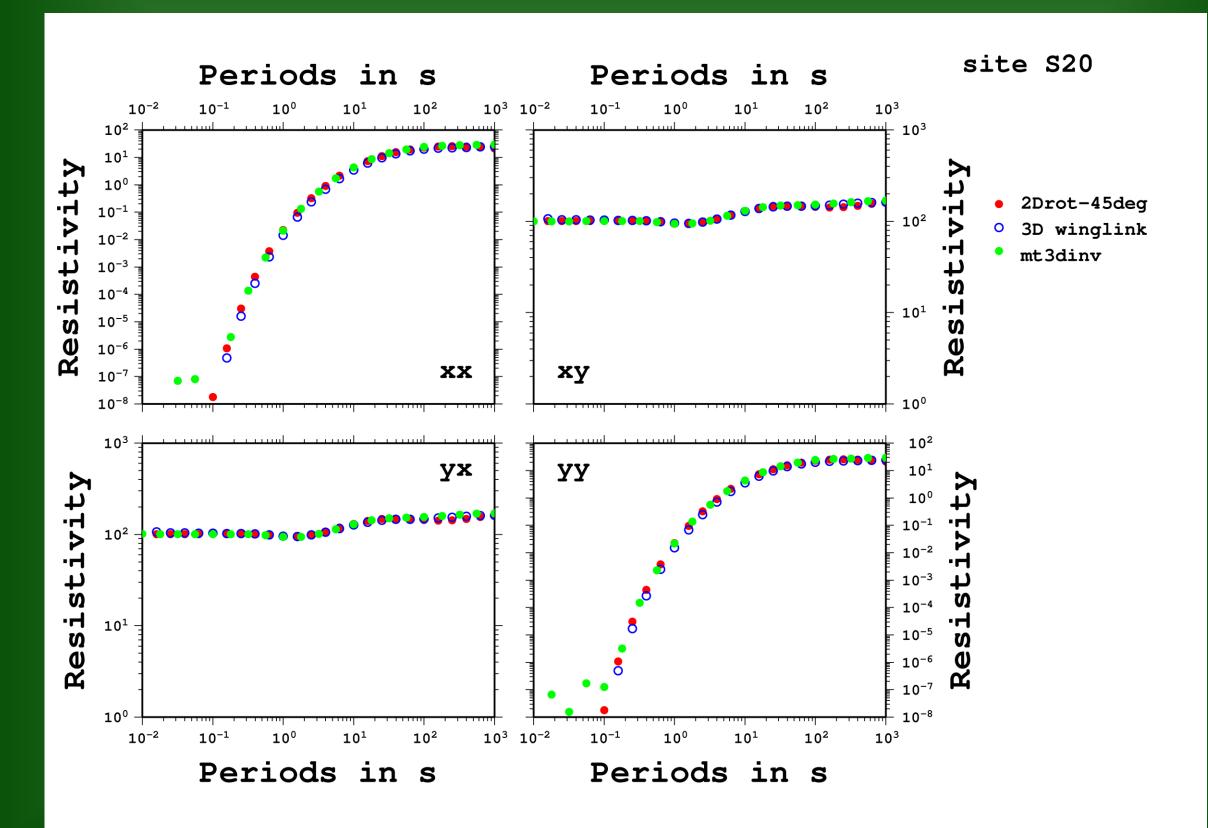
#### 3D model

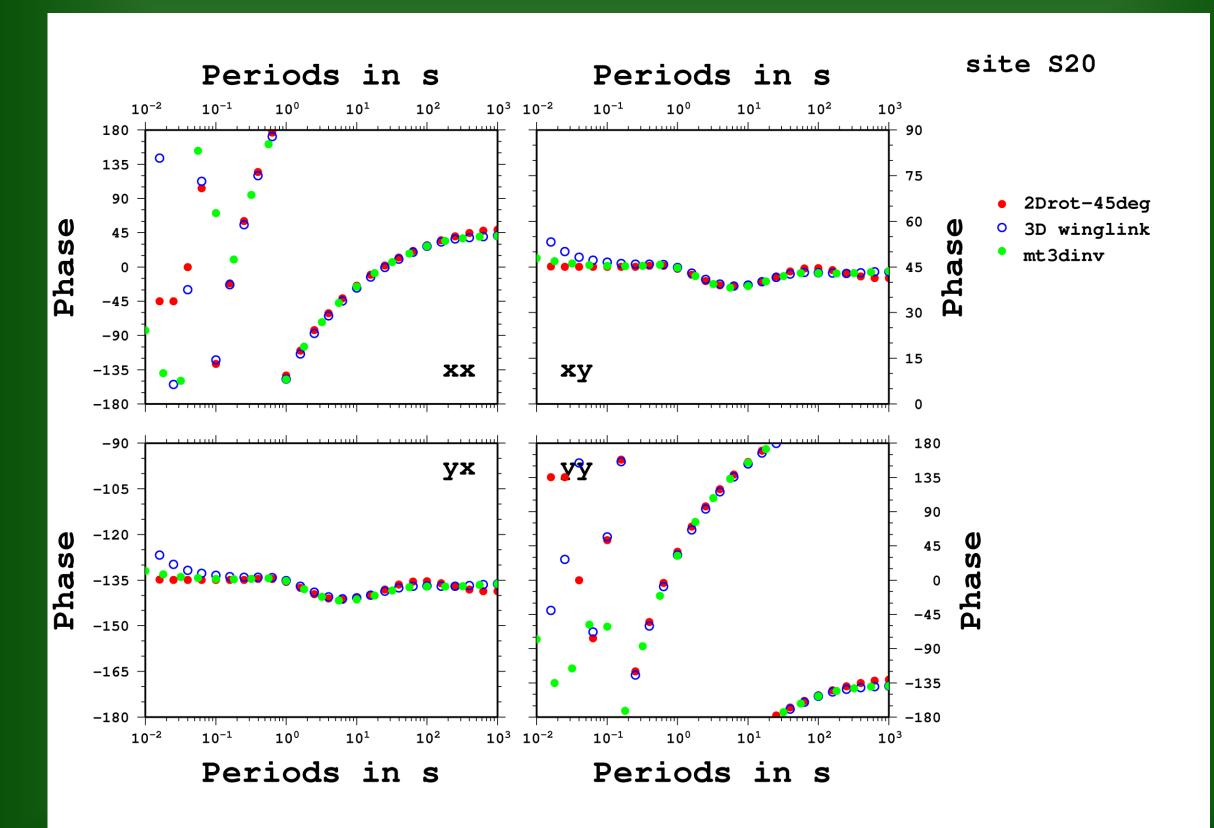
2 dykes
with NE-SW
strike
direction

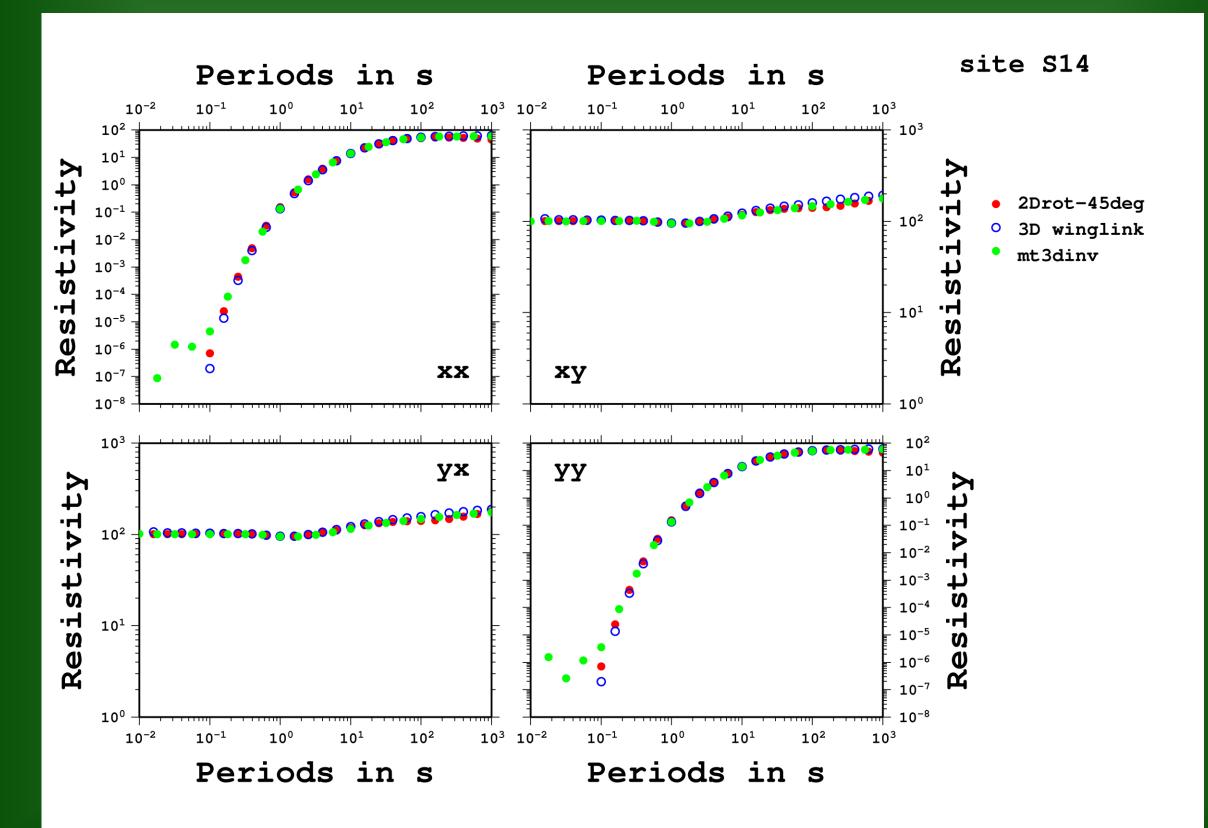
profile orientation NW-SE

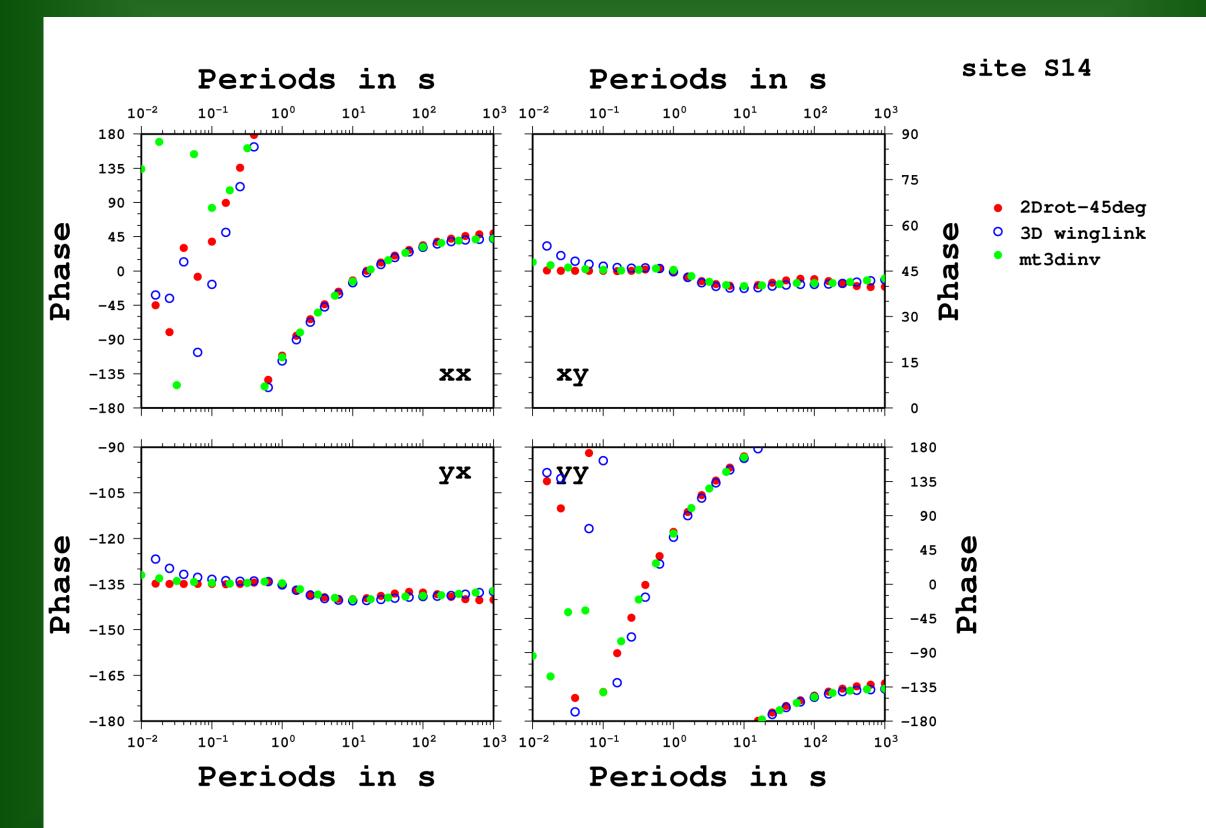


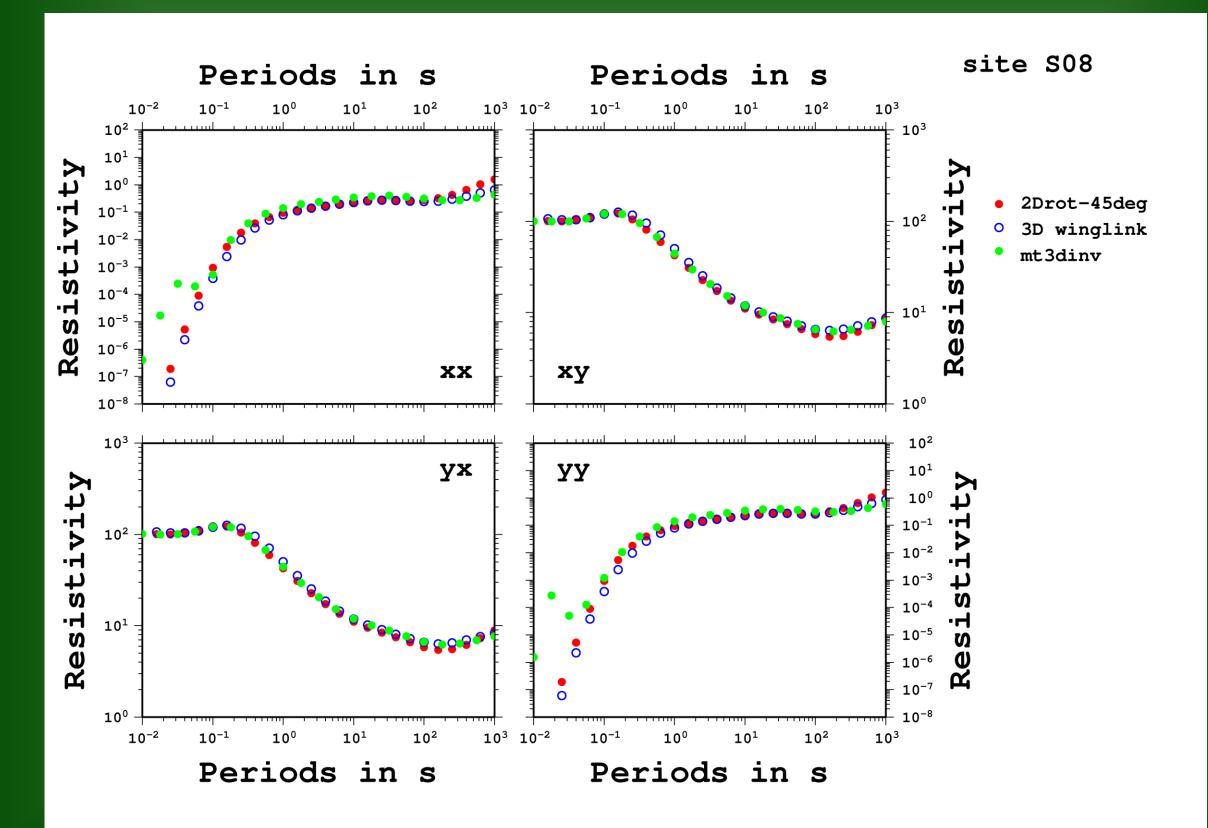


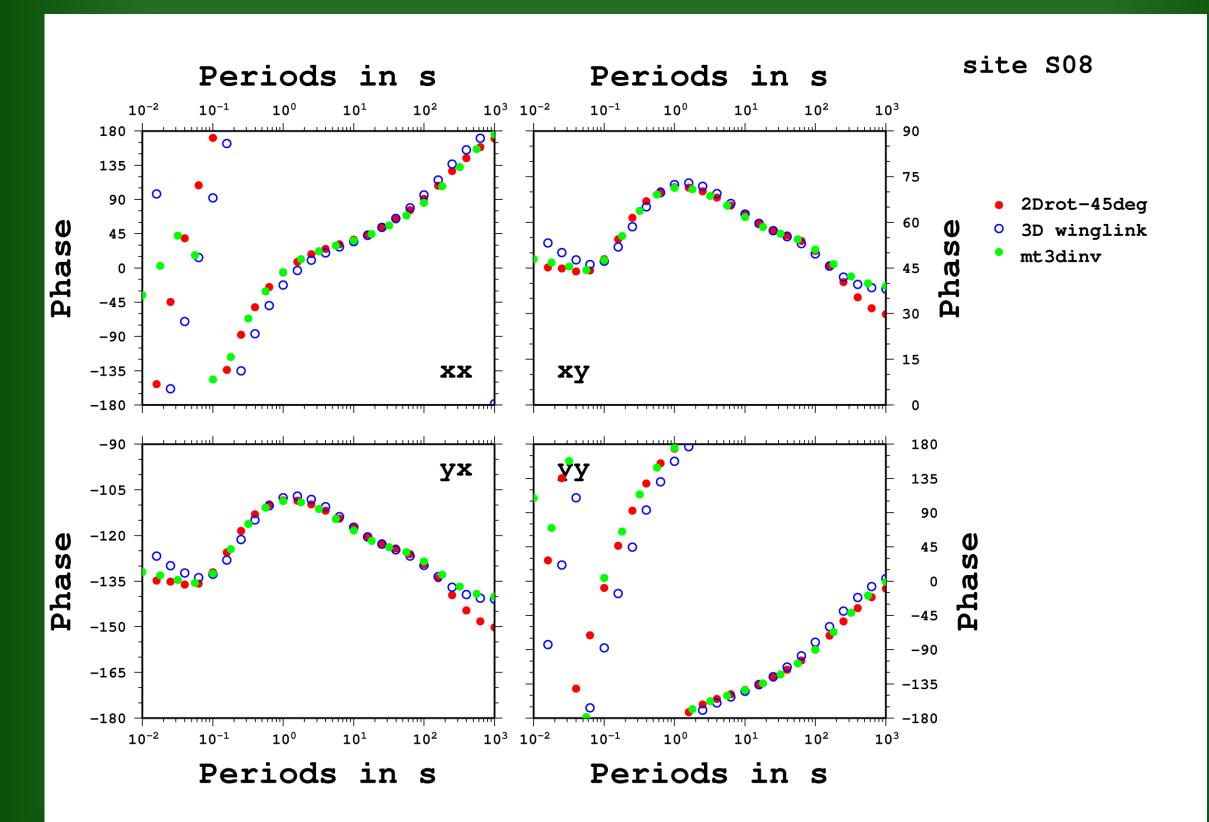












#### Conclusion

We are able to prove all 8 impedance elements and resistivity and phase curves respectively

Diagonal phase are not related to a specific quadrant

Should a threshold be introduced for the diagonal elements (based on the resistivity value)?