## How to prove the 3D forward solver? 2D vs. 3D responses

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## The first approach

2D model: $1000 \Omega$ m dyke in

3D model: same dyke structure but with different length

Idea: with increasing length approach of 3D responses to the 2D model
encture but with diferent


## Example sounding curves



## The problem

## This test ONLY addresses the off-diagonal elements!!!

## The second approach

2D modeling of real data $->$ rotate perpendicular to strike (minimize the diagonal elements)
testing the diagonal elements of the 3D solver do it the other way round


## 2D model

2 dykes with N-S strike direction

## profile orientation W-E

## Rotation of the

## coordinate system

$$
\begin{gathered}
\mathbf{Z}_{2 D r o t}=\mathbf{R} \mathbf{Z}_{2 D} \mathbf{R}^{\prime} \\
\mathbf{R}=\left(\begin{array}{cc}
\cos \theta & \sin \theta \\
-\sin \theta & \cos \theta
\end{array}\right)
\end{gathered}
$$




## 3D model

## 2 dykes <br> with NE-SW strike direction

## profile

 orientation NW-SE
## Site S01



## Site S01



## Site 520



## Site S20



## Site S14



## Site S14



## Site 508



## Site 508



## Conclusion

We are able to prove all 8 impedance elements and resistivity and phase curves respectively

## Diagonal phase are not related to a specific quadrant

Should a threshold be introduced for the diagonal elements (based on the resistivity value)?

