Comparison of 3D forward responses

The MT 3D inversion workshop test model

designed by Marion Miensopust, Pilar Queralt and Alan Jones

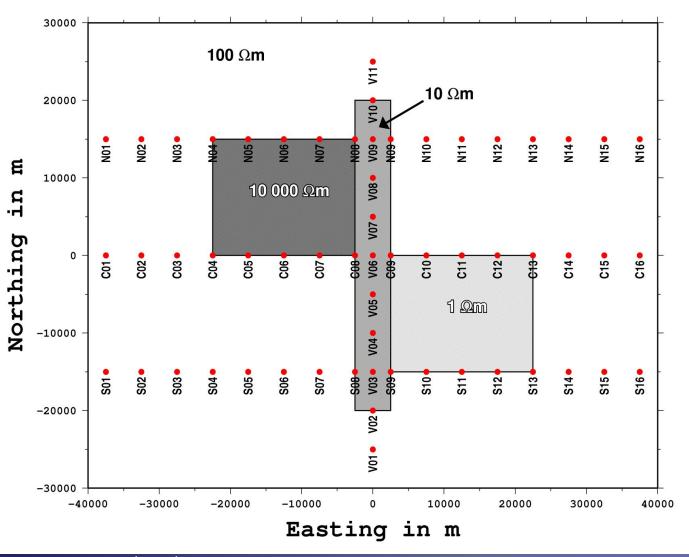
Site locations

59 sites

21 periods

4 periods per decade

0.1 s – 10000 s

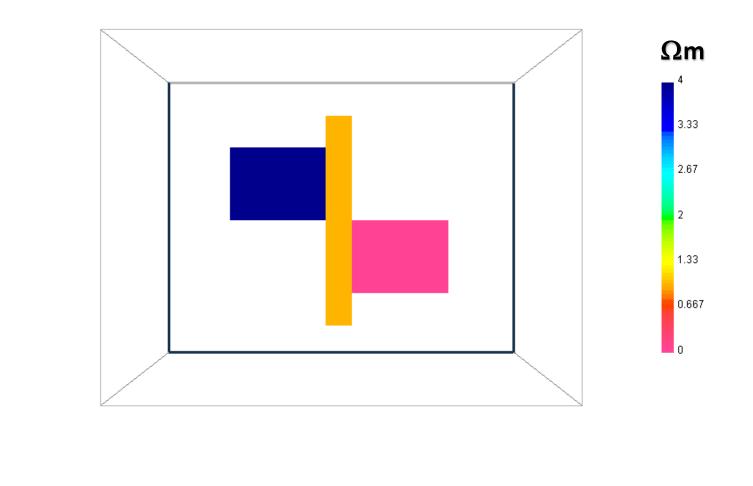


Forward model

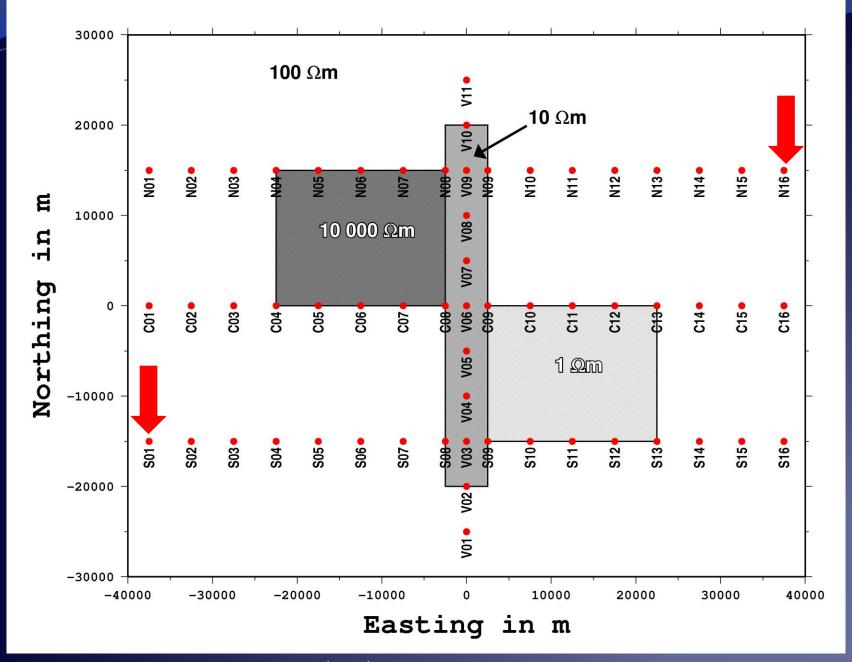
Depth = 0 Ωm 3.33 2.67 2 1.33 0.667 0

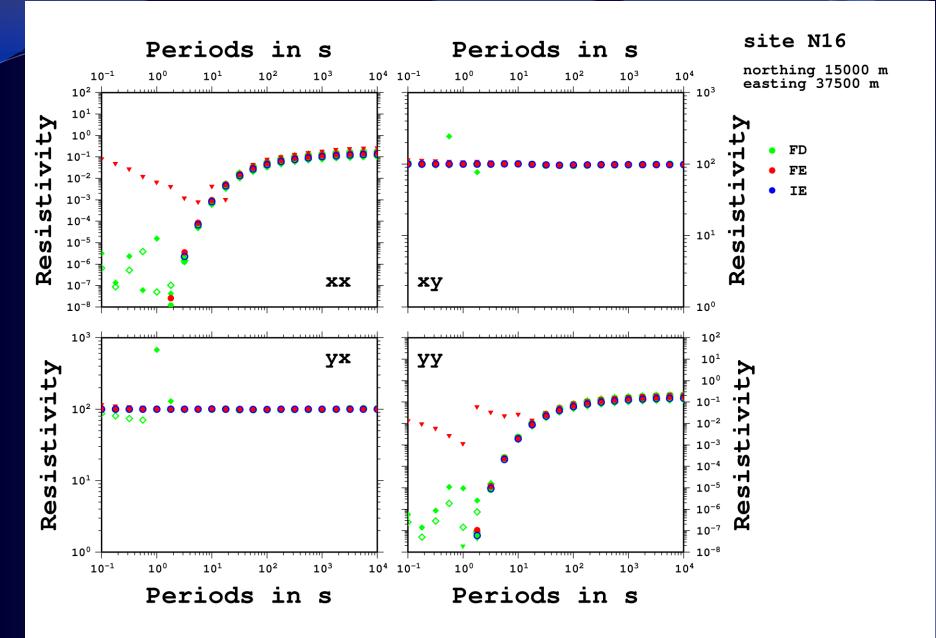
Forward model

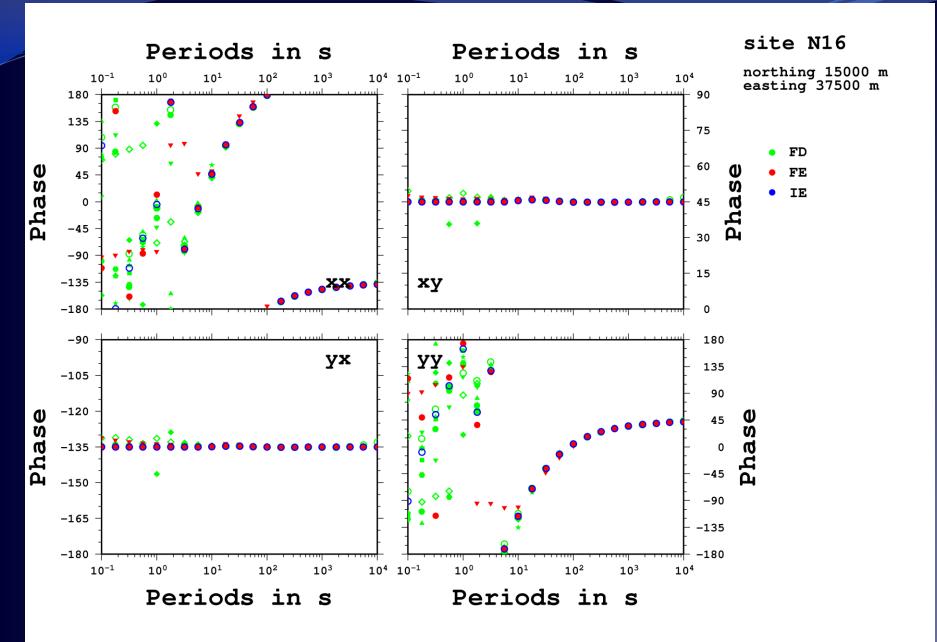
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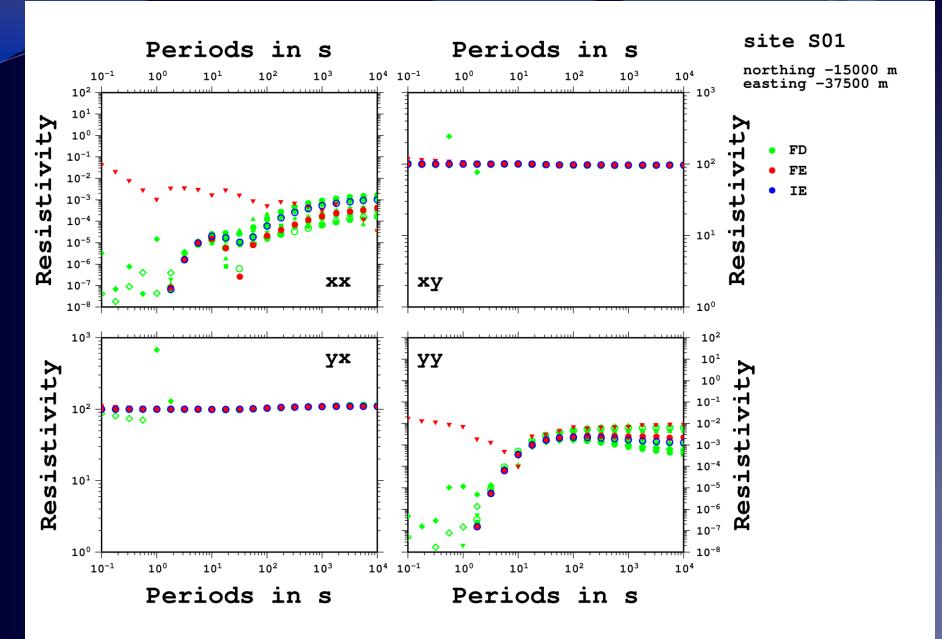


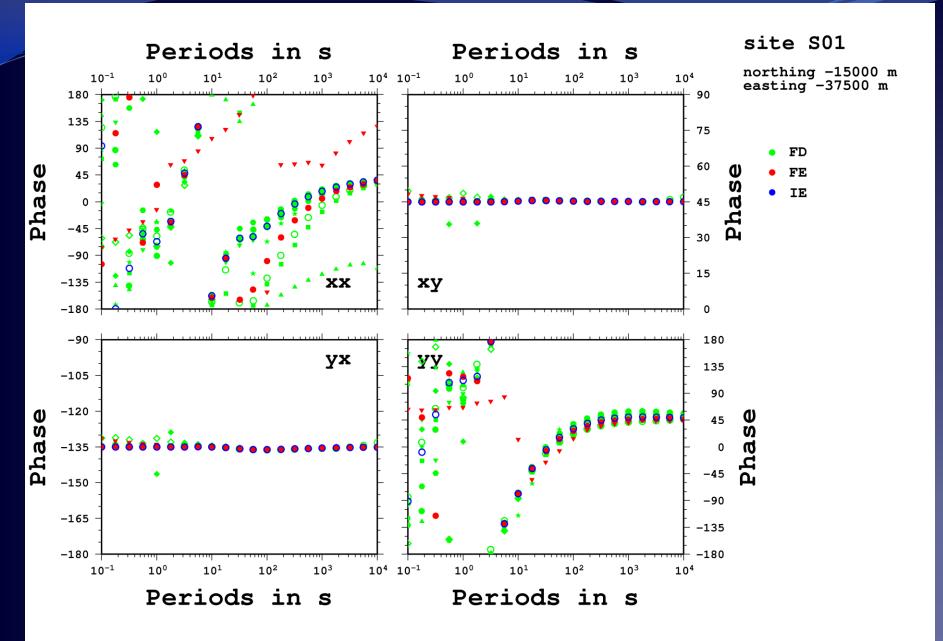
Name	Code	CPU time	Mesh	Info
Colin Farquharson	FD (mt3dinv-UBC GIF)		72 x 72 x 72 109 x 110 x 110	
Elliot Holtham & Doug Oldenburg	FD (mt3dinv-UBC GIF)	49 h 37 min		Dual AMD 244 Opteron CPU, 4GB RAM
Randy Mackie	FD	30 min	95 x 95 x 73 (without air layers)	36 dual processor Xeons, 3.2 GHz
Naser Meqbel	FD		42 x 42 x 56 (plus 10 air layers)	
Marion Miensopust	FD (WinGlink)	51 min	85 x 62 x 34 (plus 10 air layers)	Intel Core2 CPU E6300, 1.86GHz, 3.25 GB RAM
	FD (mt3dinv-UBCGIF)		92 x 58 x 37	
	FD (wsinv3dmt)	1 h 18 min	39 x 40 x 18 (plus 7 air layers)	Intel Core2 CPU E6300, 1.86GHz, 3.25 GB RAM
Greg Newman	FD	4 min - 38 min per period		Parallel Linux cluster using 64 cores
Yutaka Sasaki	FD	1 h 14 min	65 x 83 x 51	Pentium 4 PC, 2GB RAM
Antje Franke	FE	7 h 40 min	61000/87000 degrees of freedom	PC with AMD Athlon 3200+ Processor, 3GB RAM
Nuree Han & Tae Jong Lee	FE (EG3DTMT)	57 h 16 min	48 x 47 x 31	Cluster: 256 nodes IBM x335 server, 2 CPUs each (Pentium IV Xeon DP 2.8 GHz
Dmitry Avdeev	IE (x3d)	4 h 11 min	120 x 135 x 23	Laptop with T7200 2GHz CPU, 2GB RAM

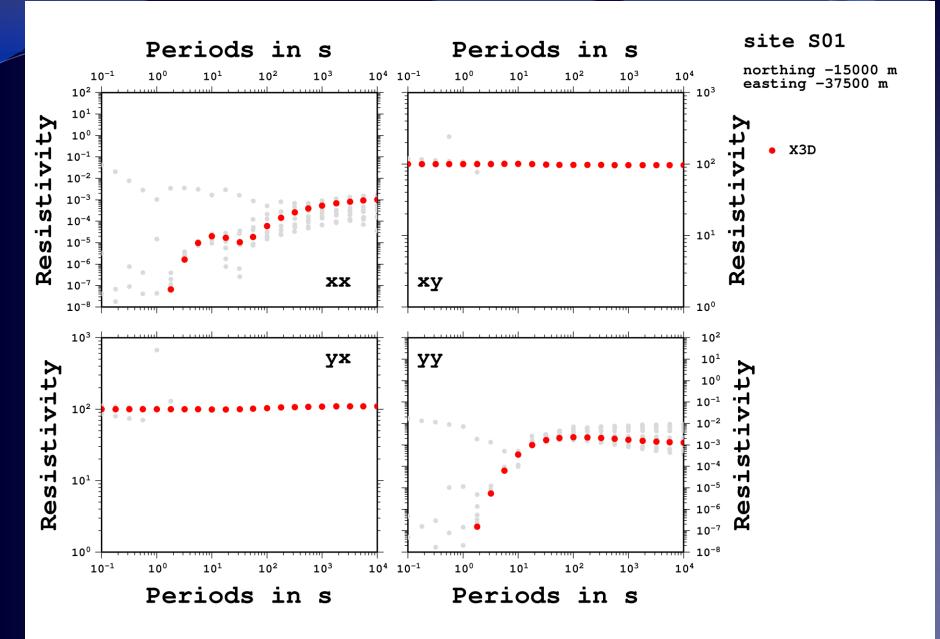


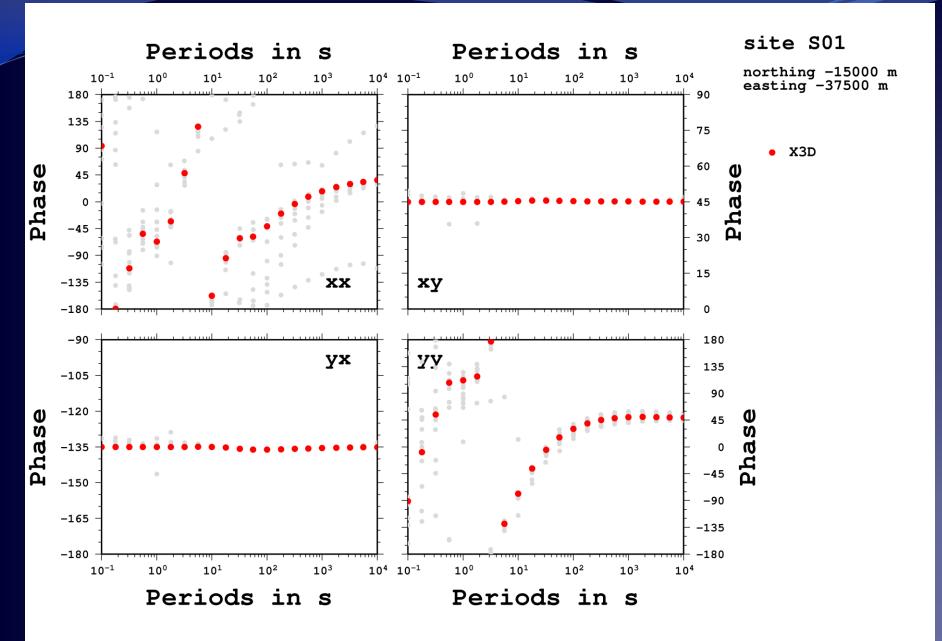


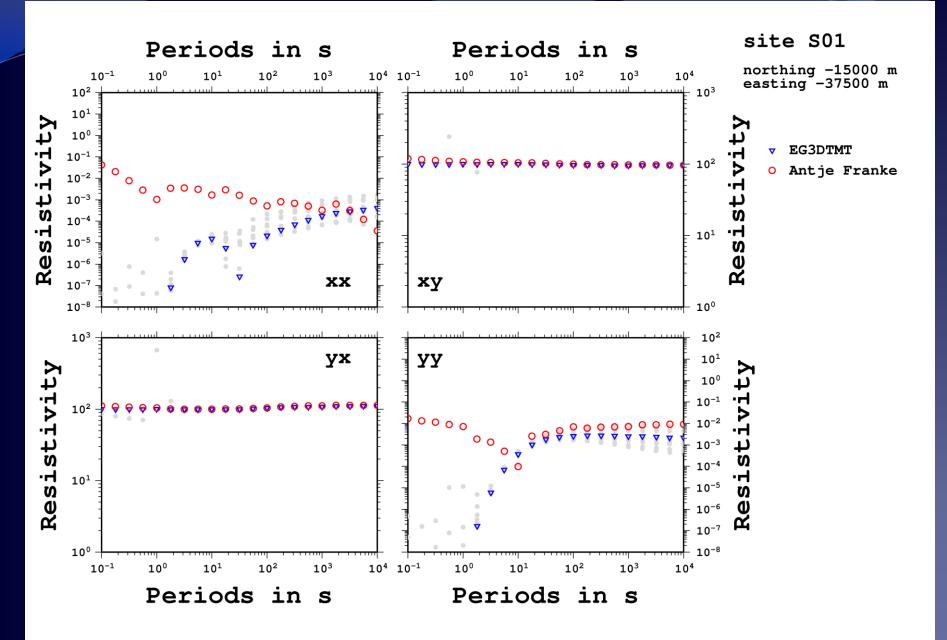


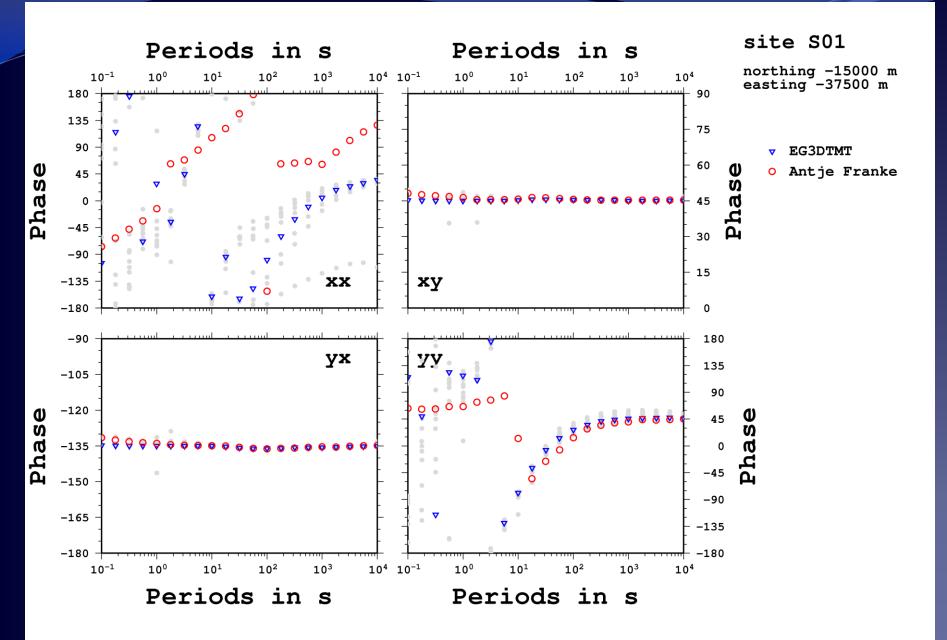


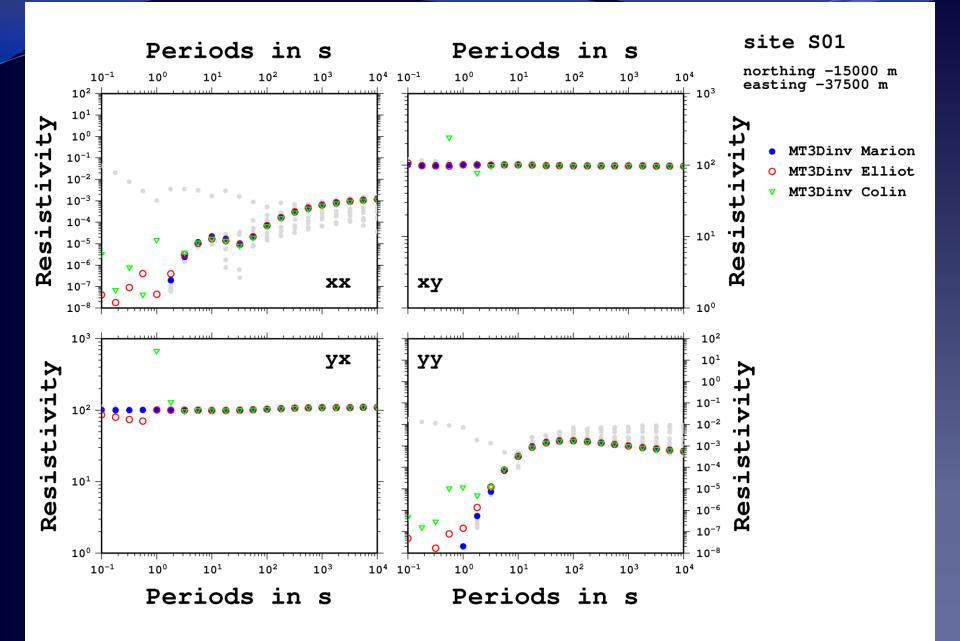


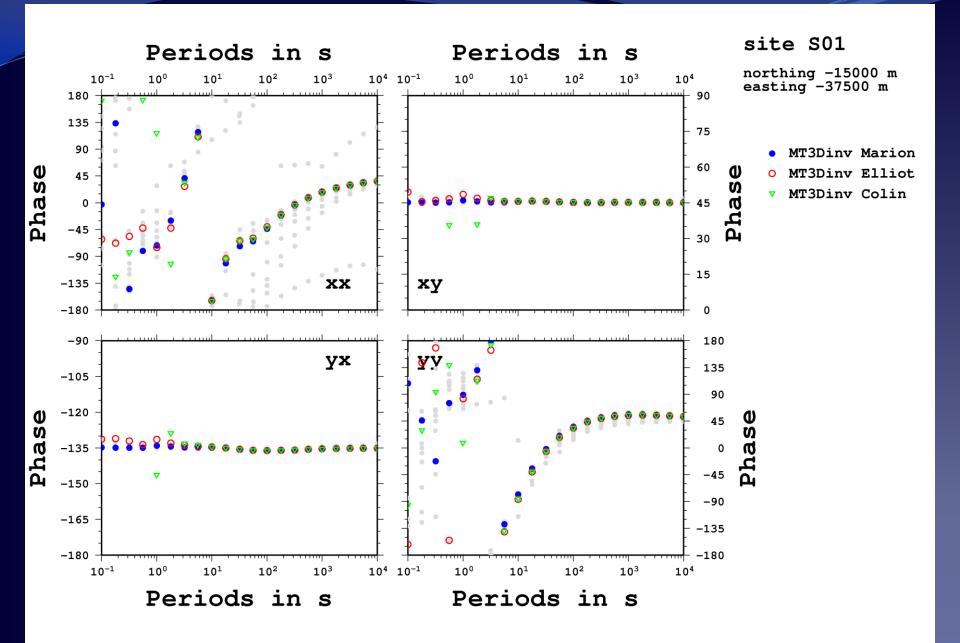


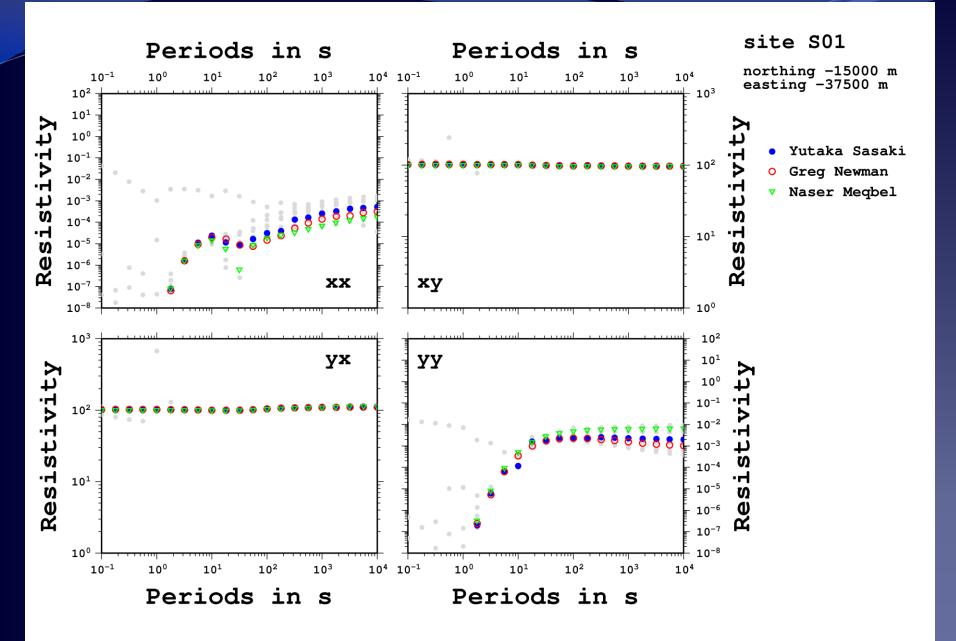


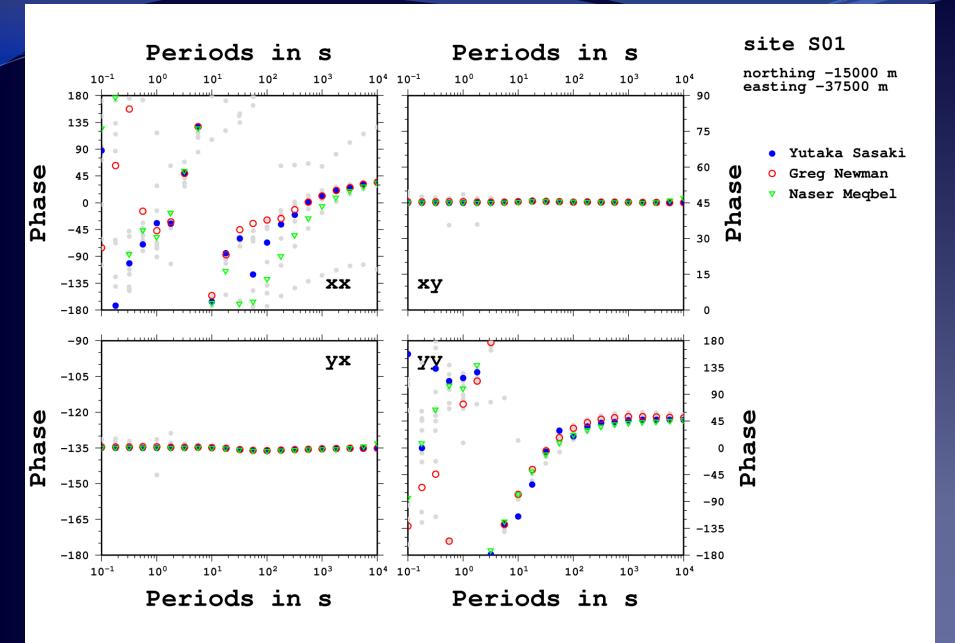


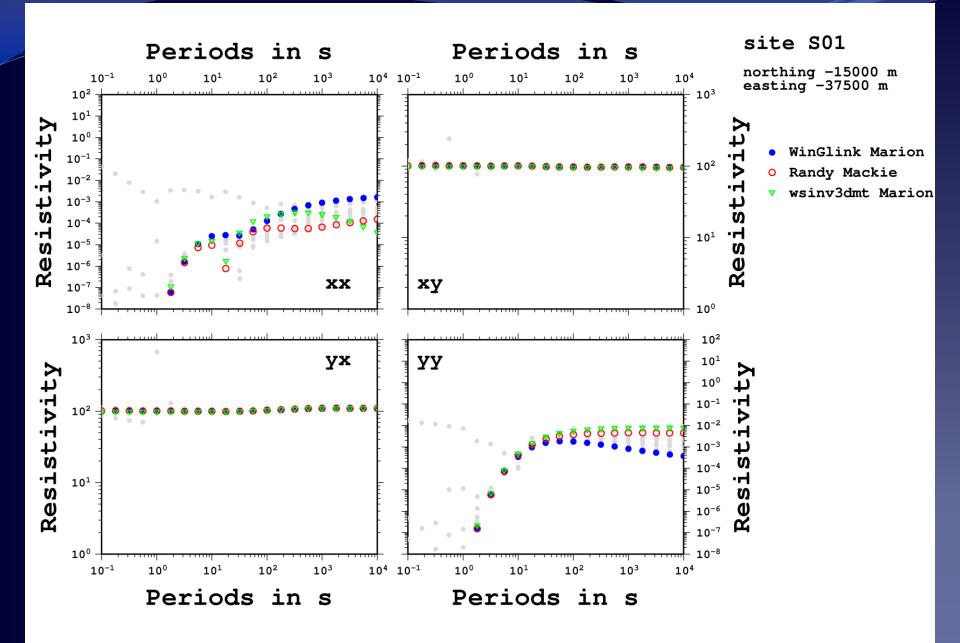


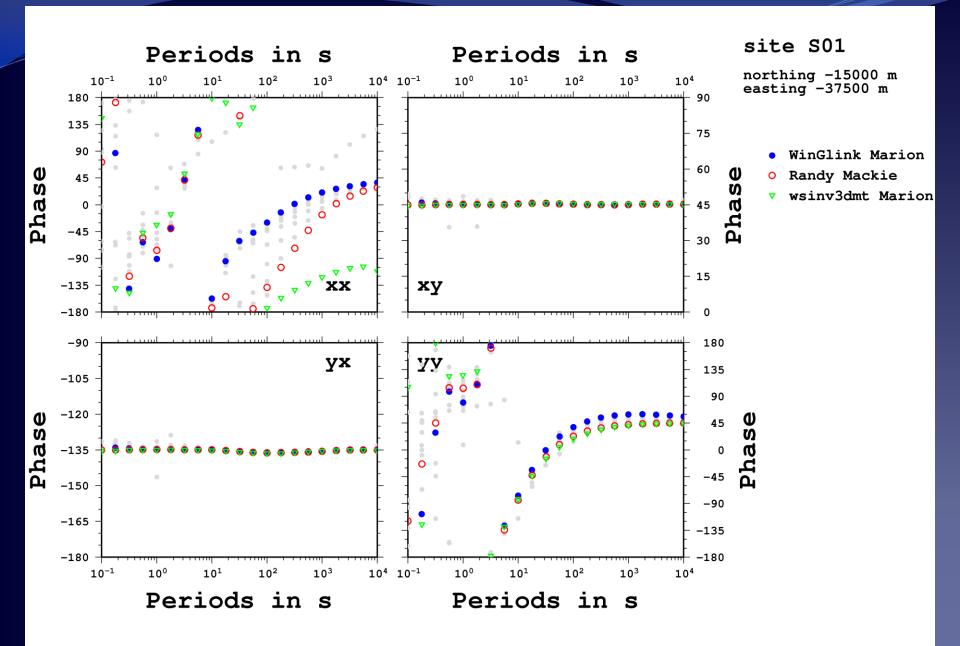


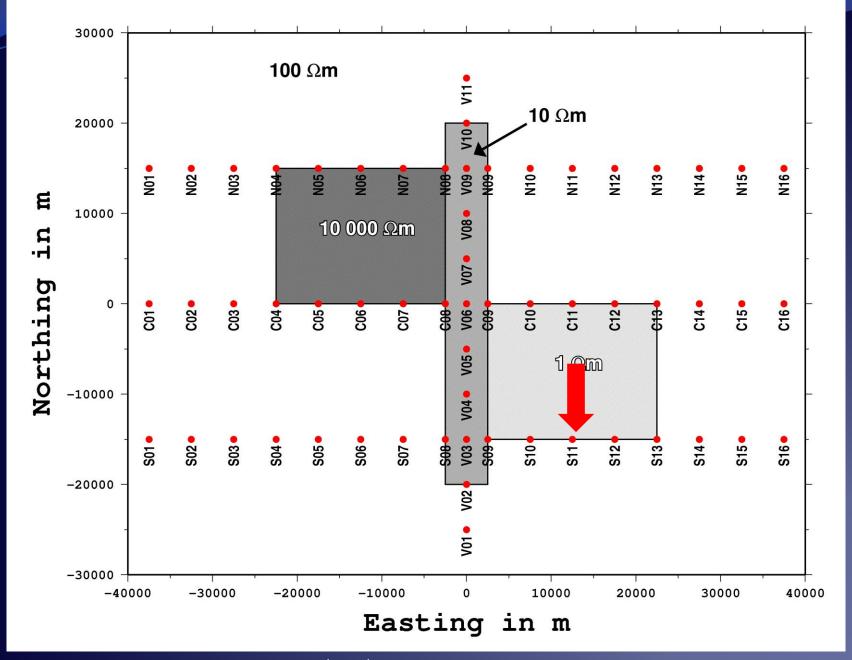


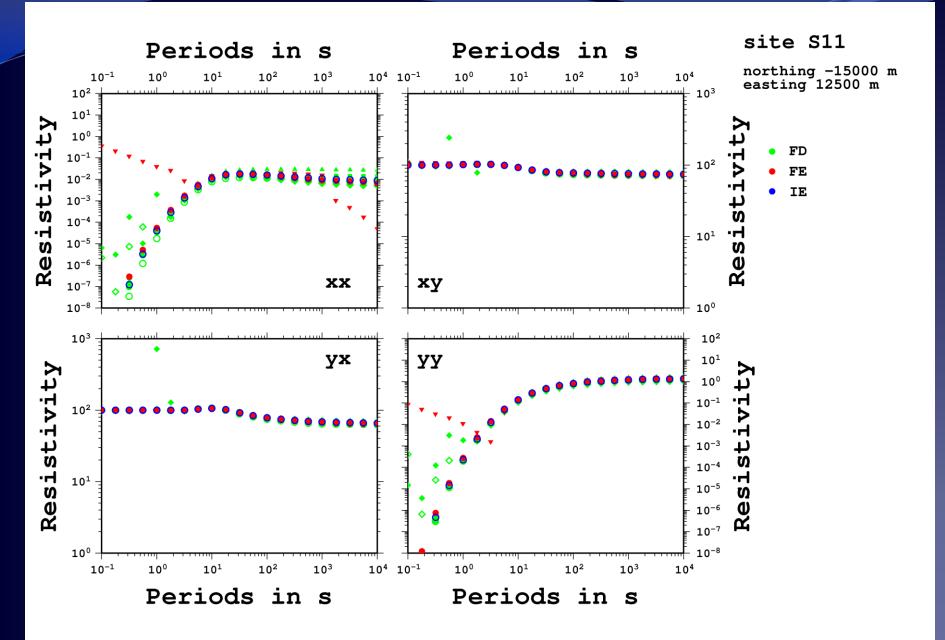


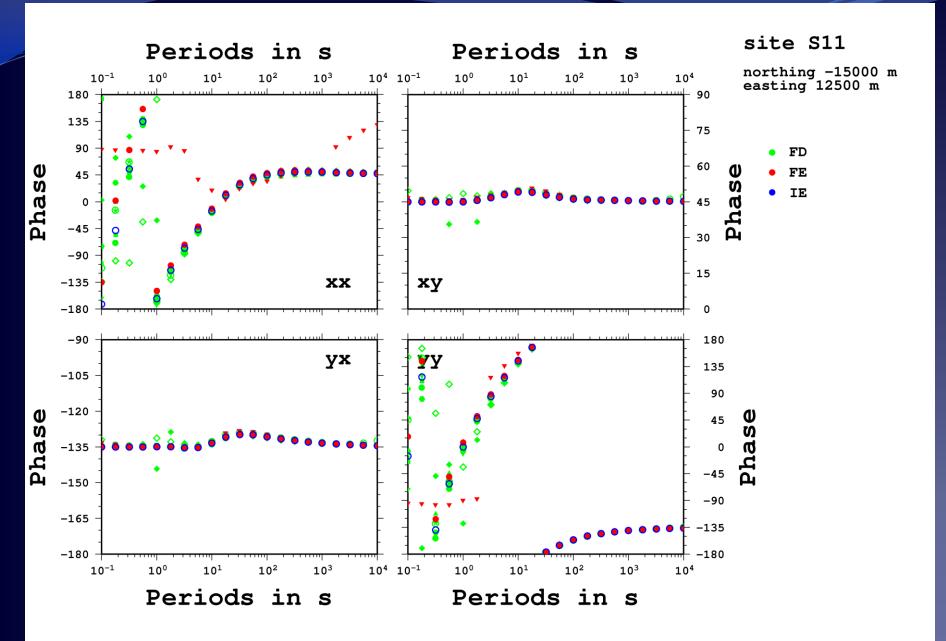


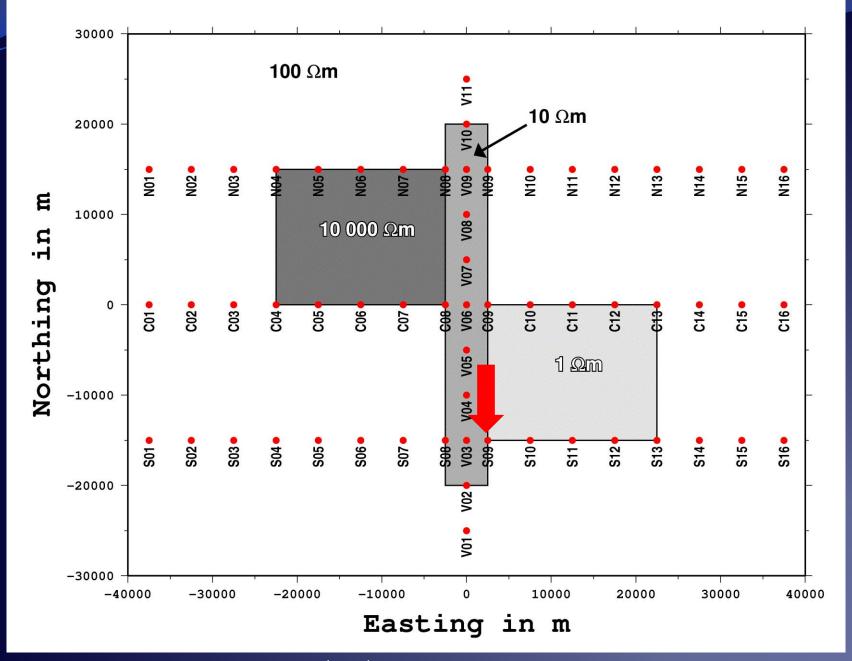


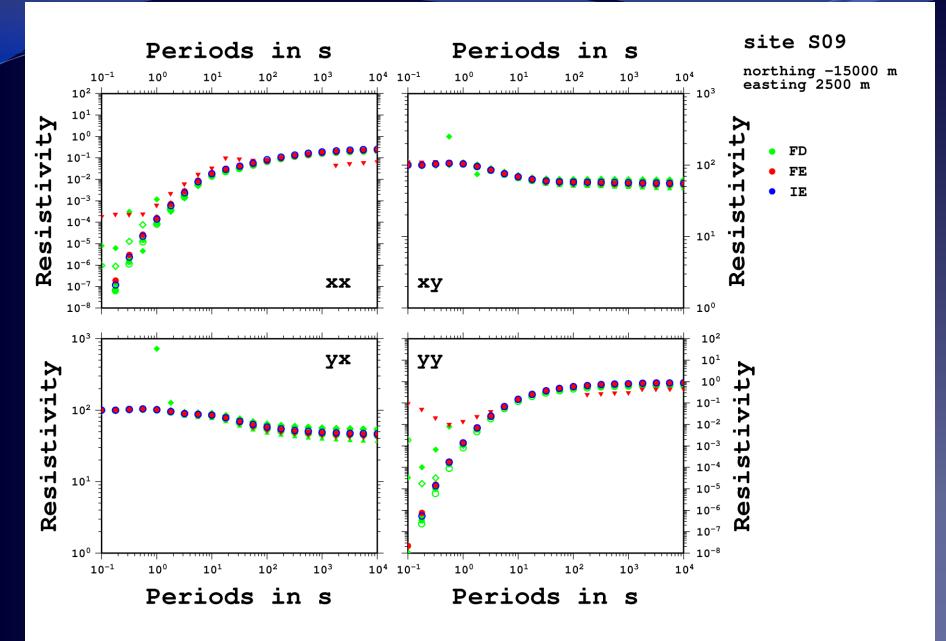


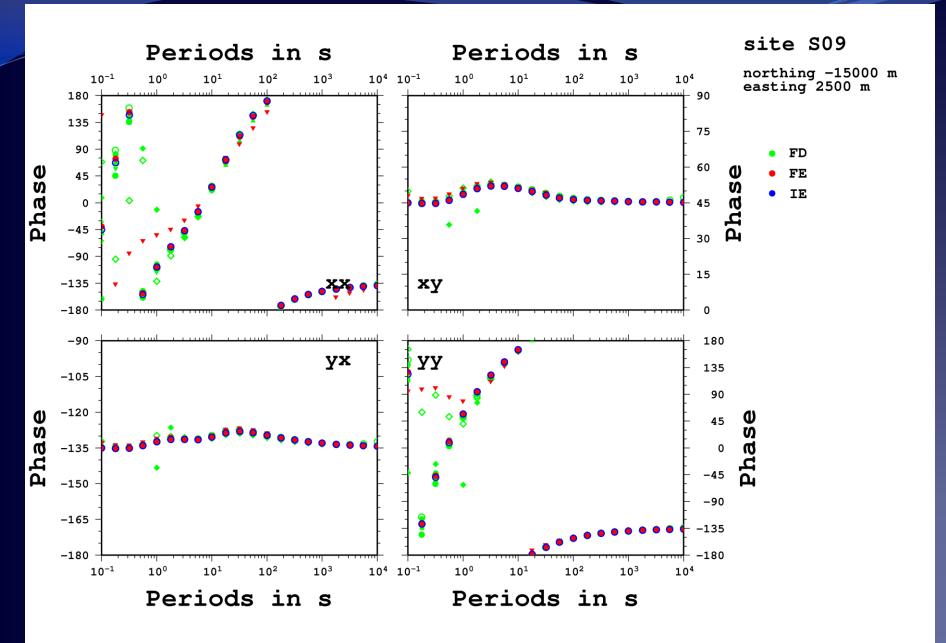


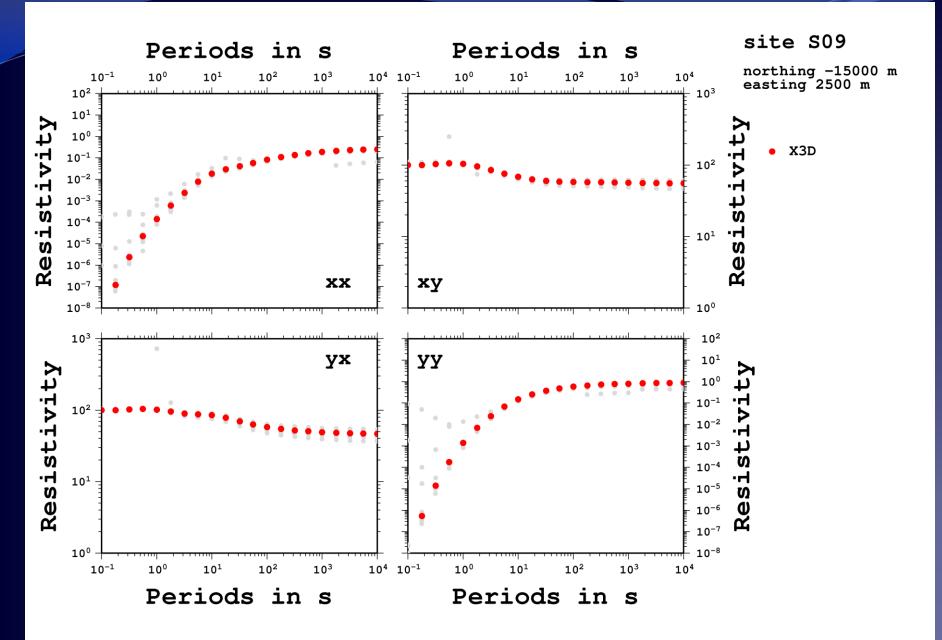


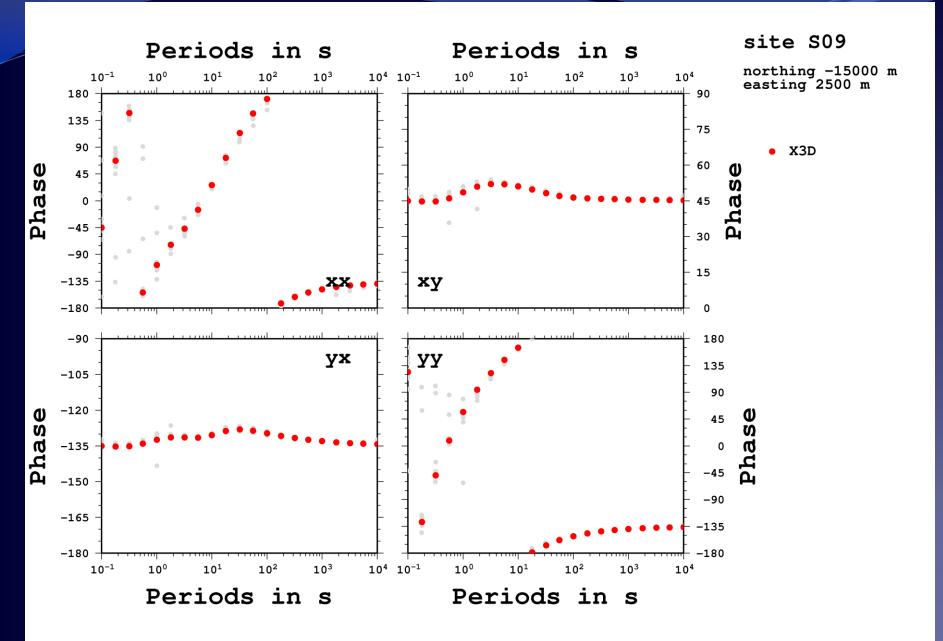


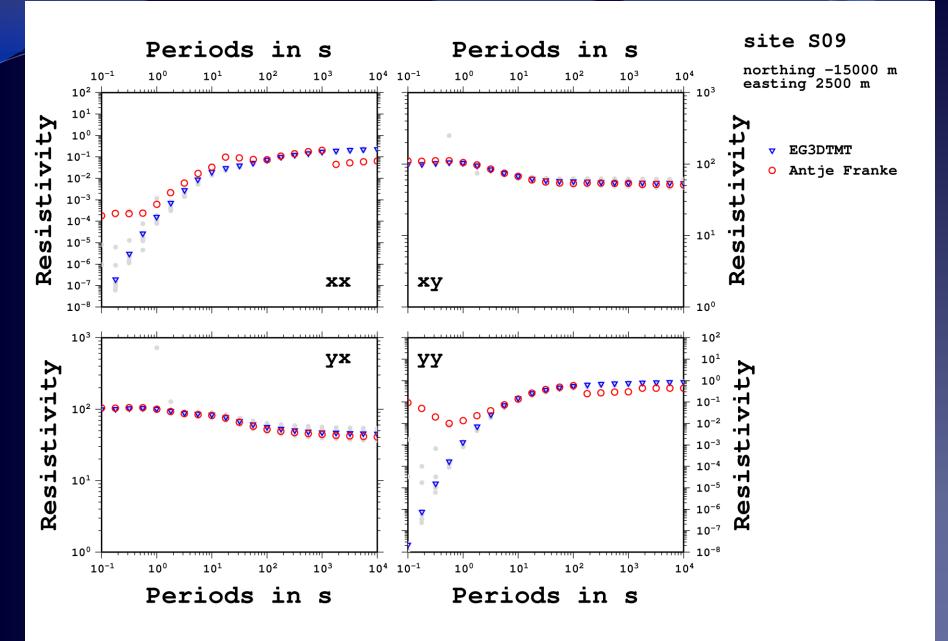


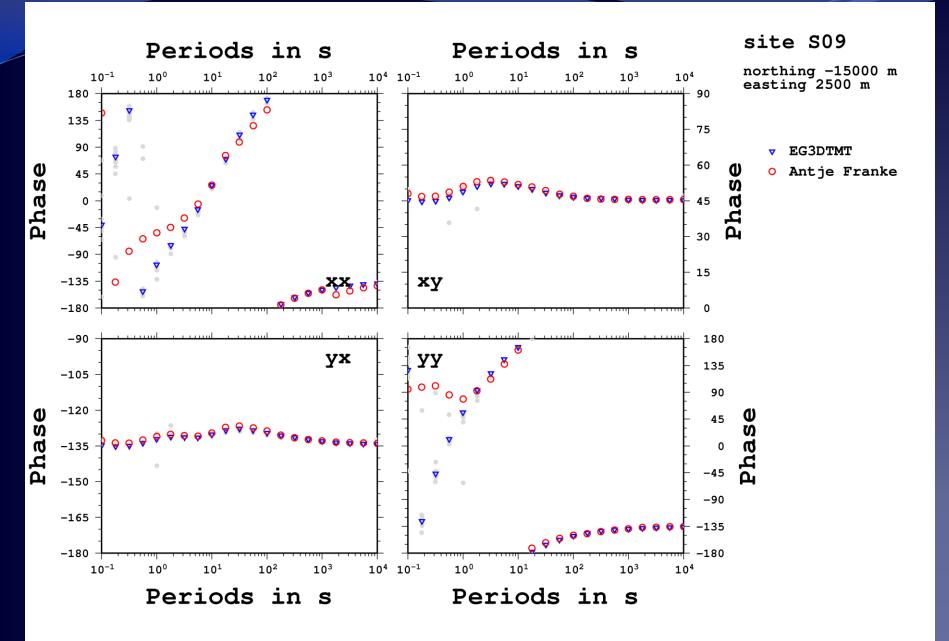


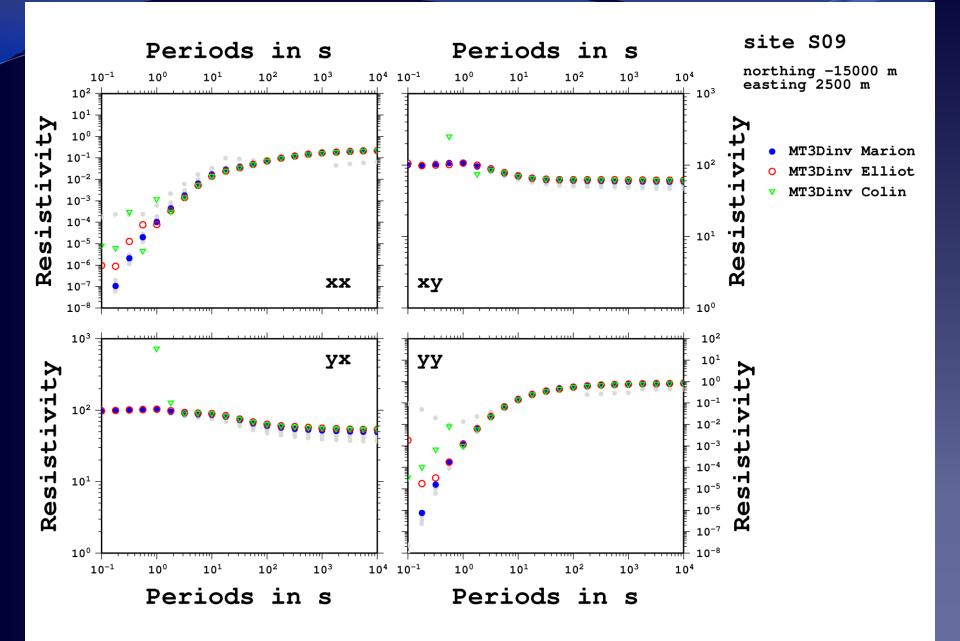


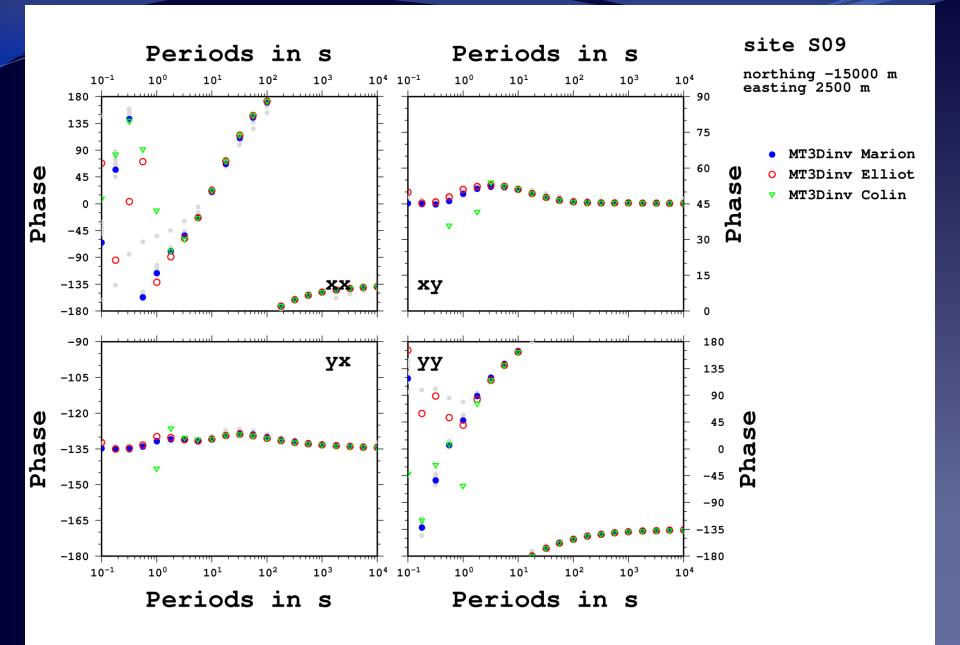


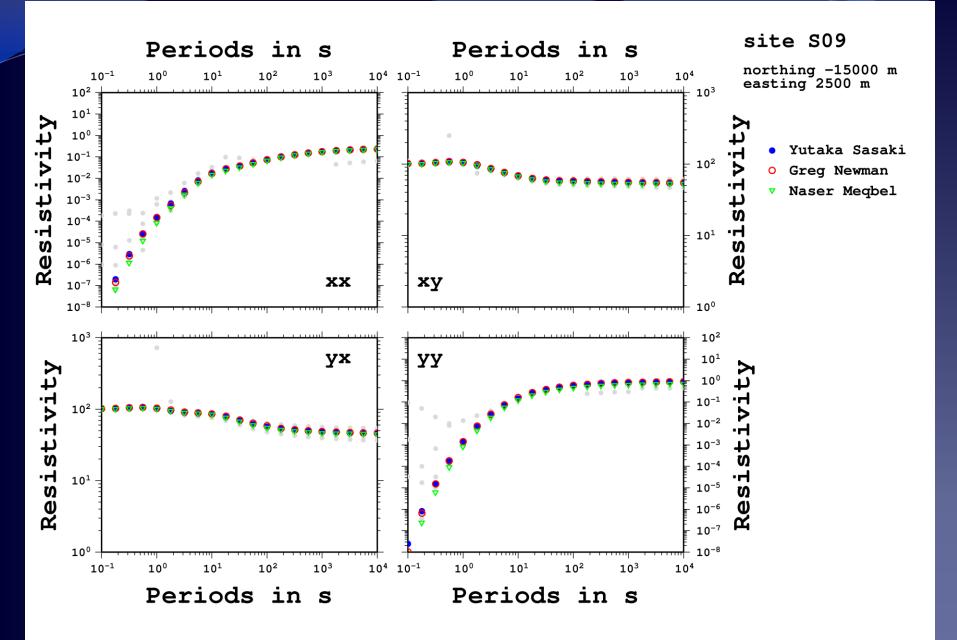


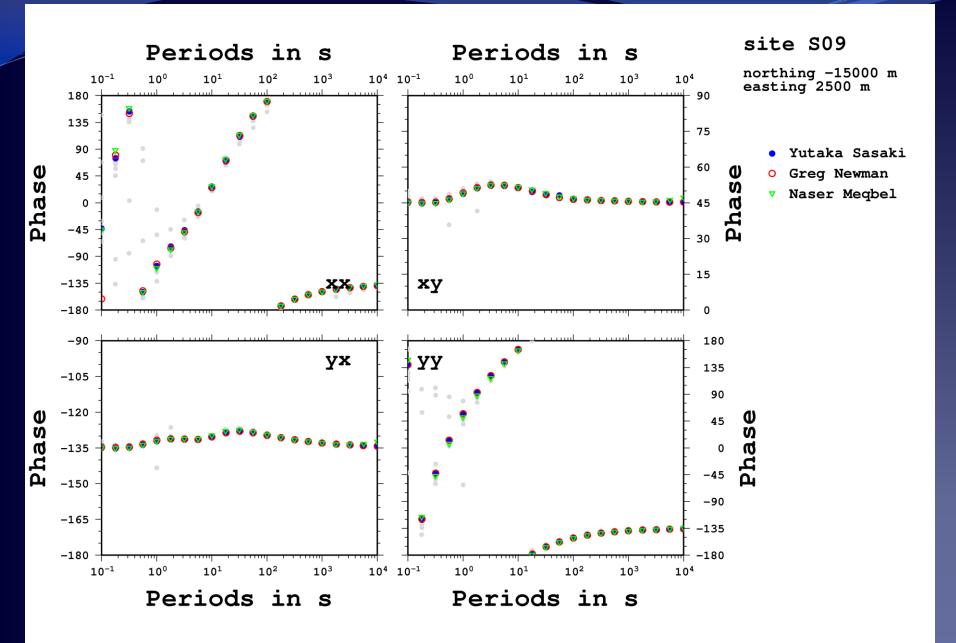


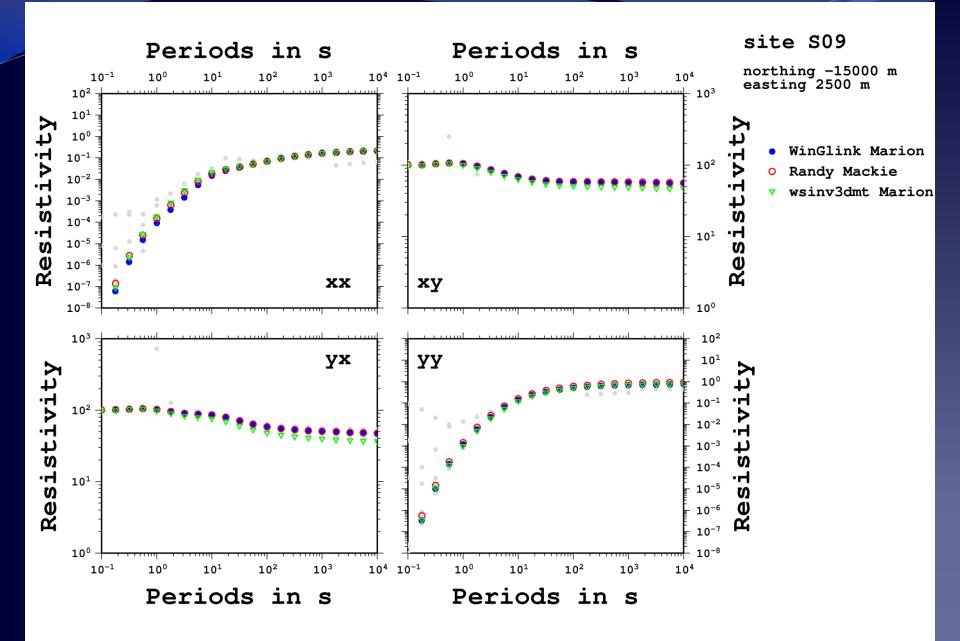


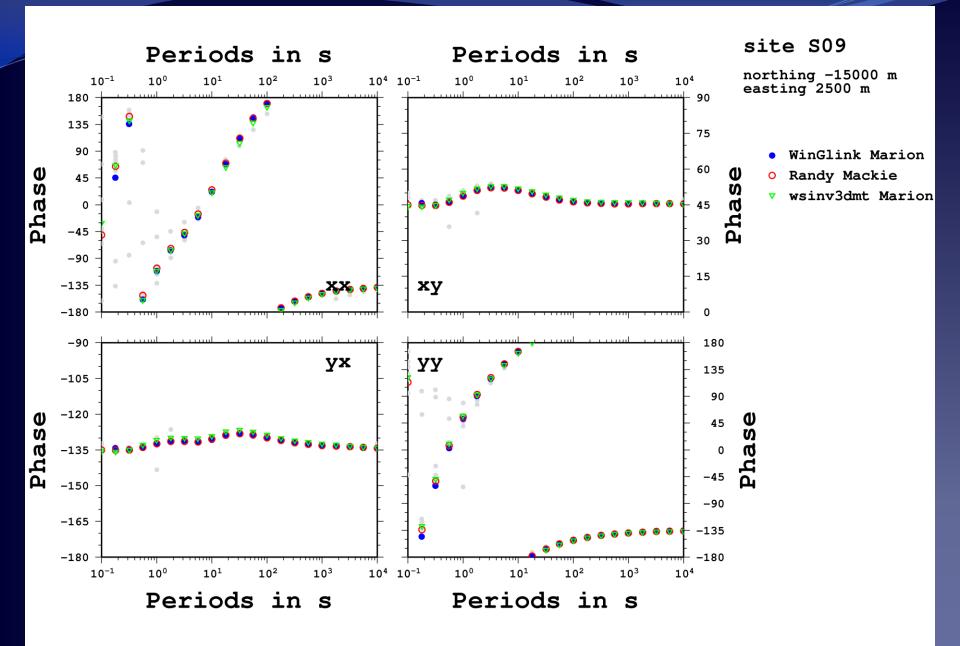


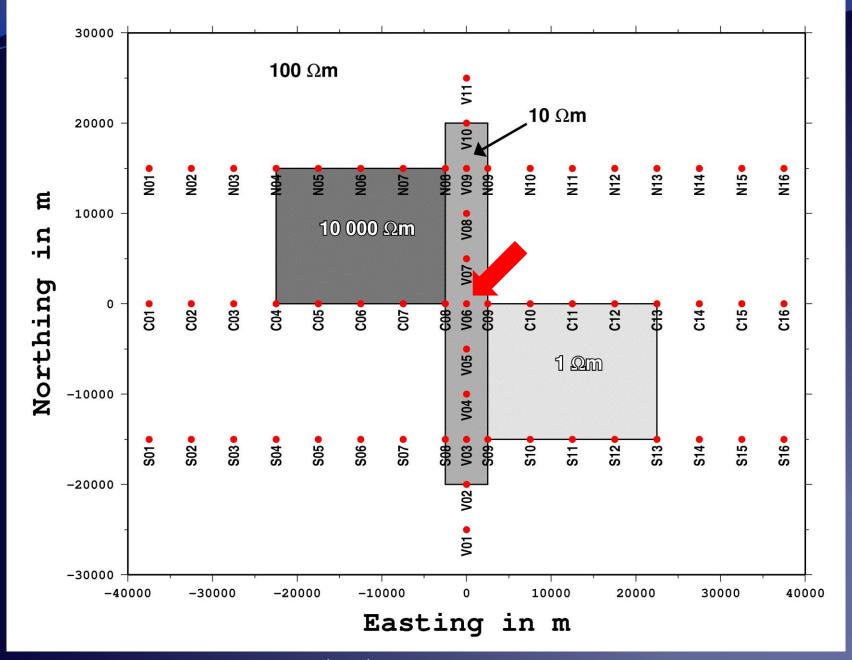


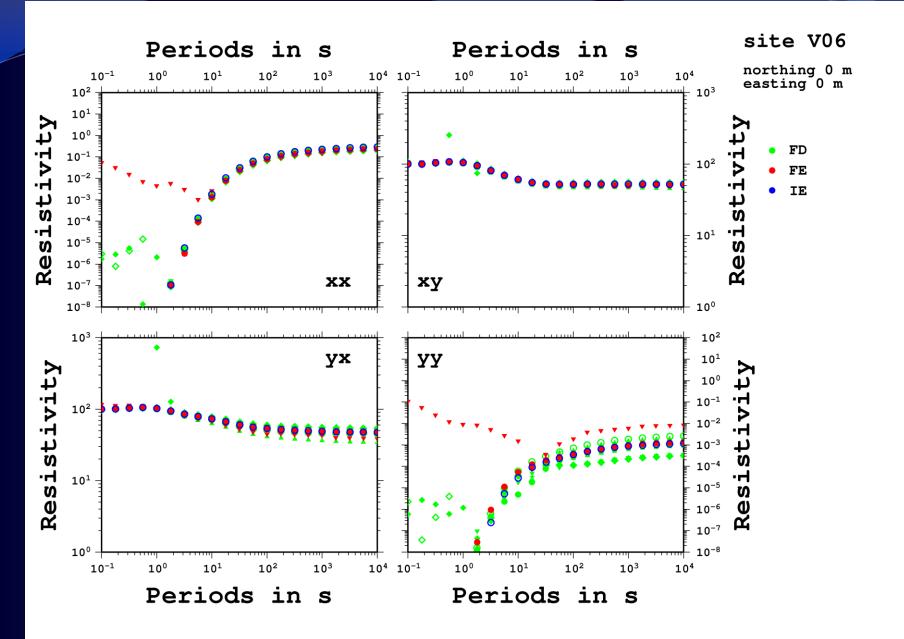


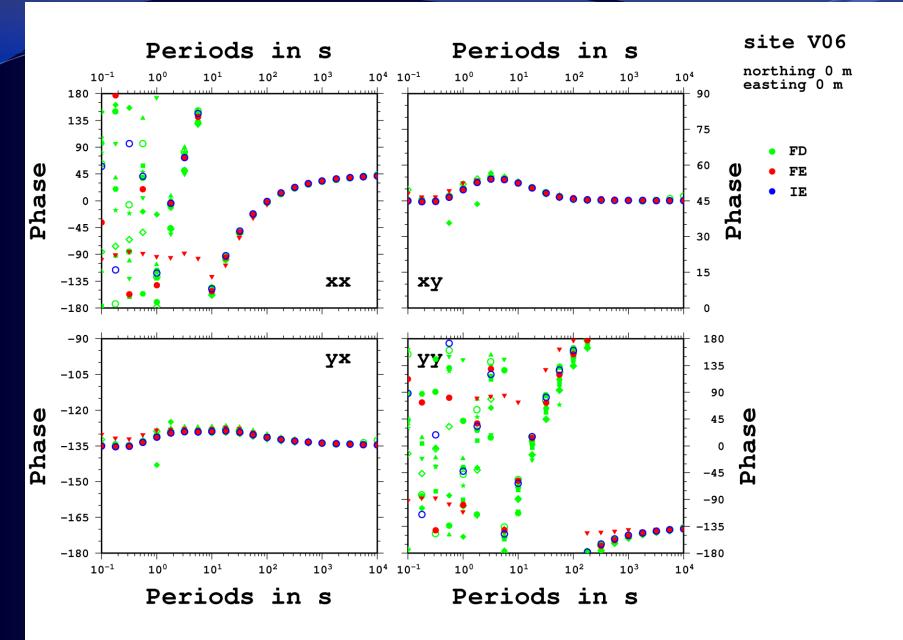


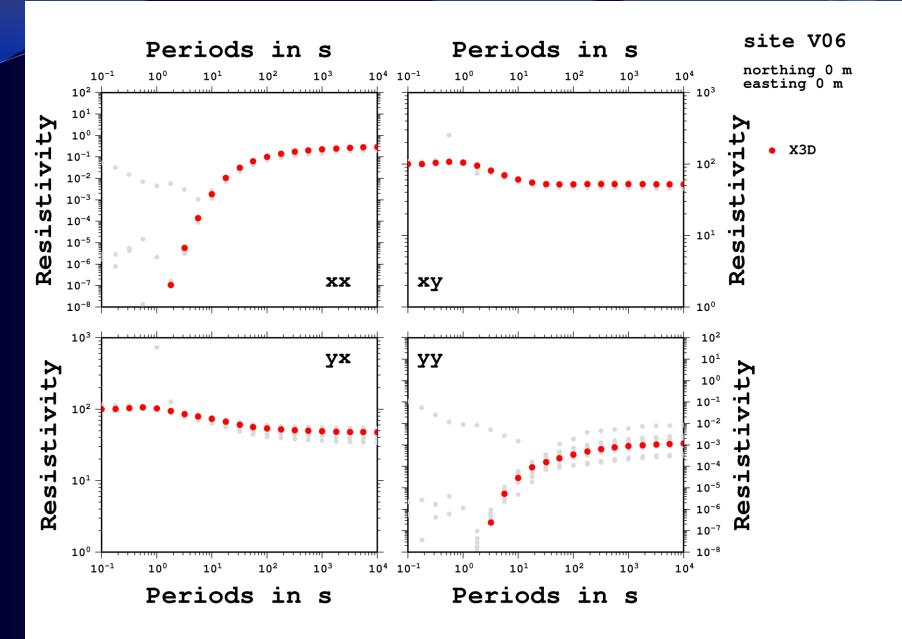


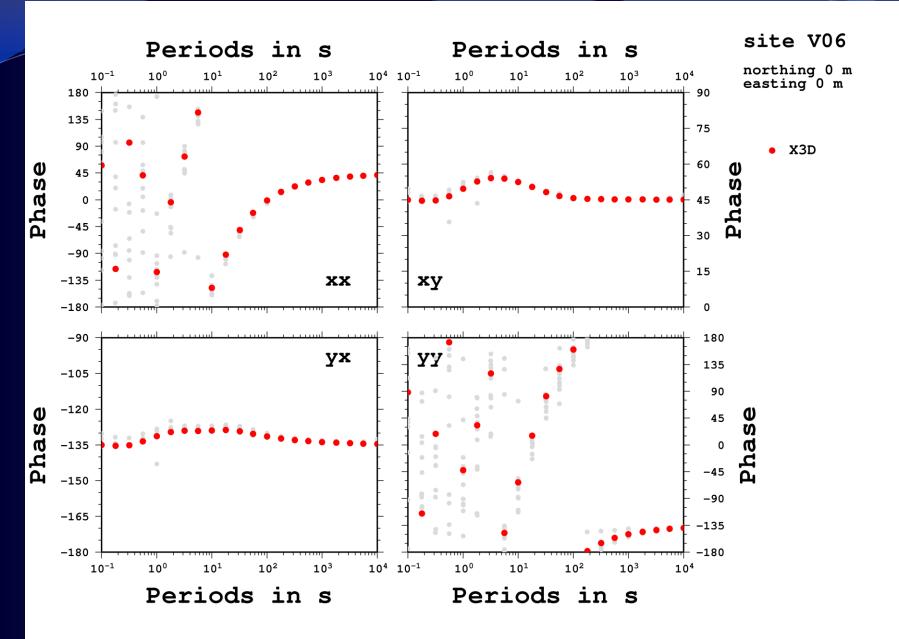




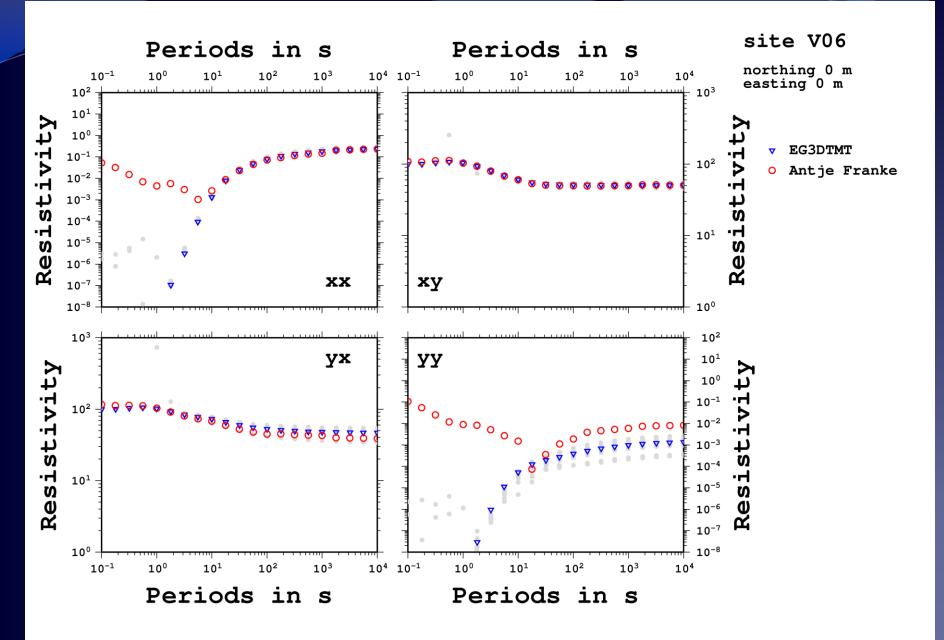


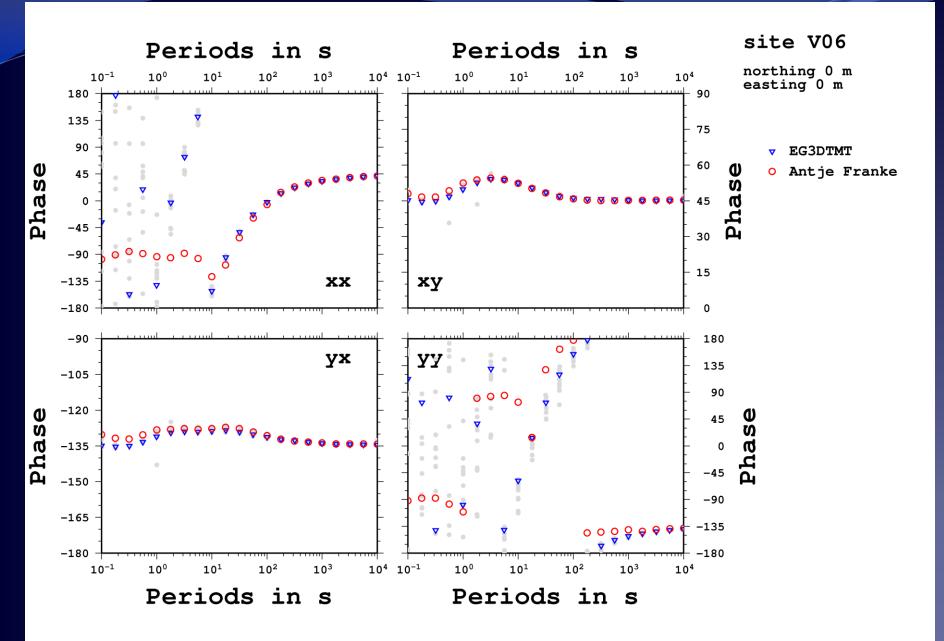


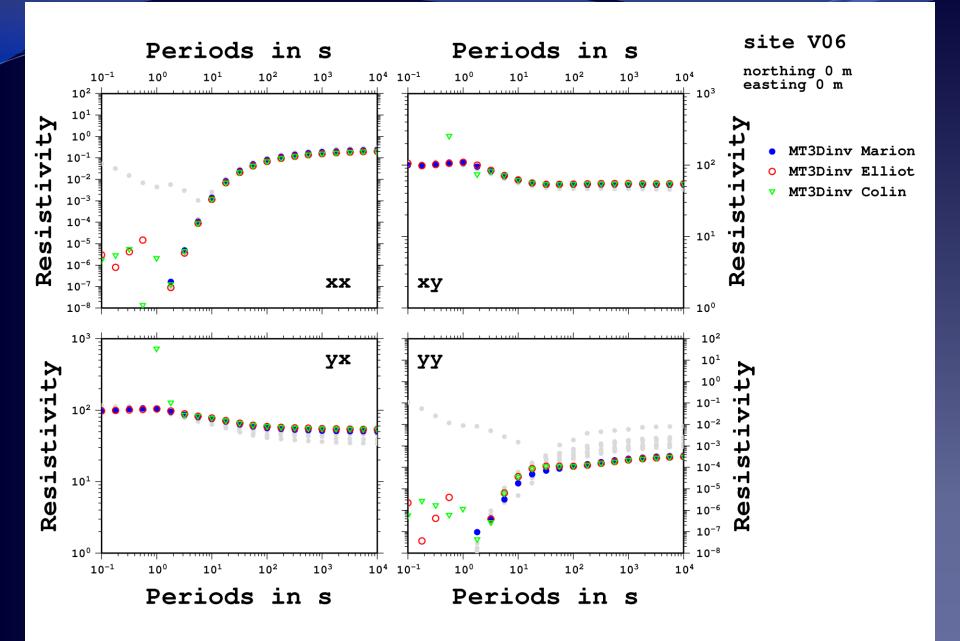


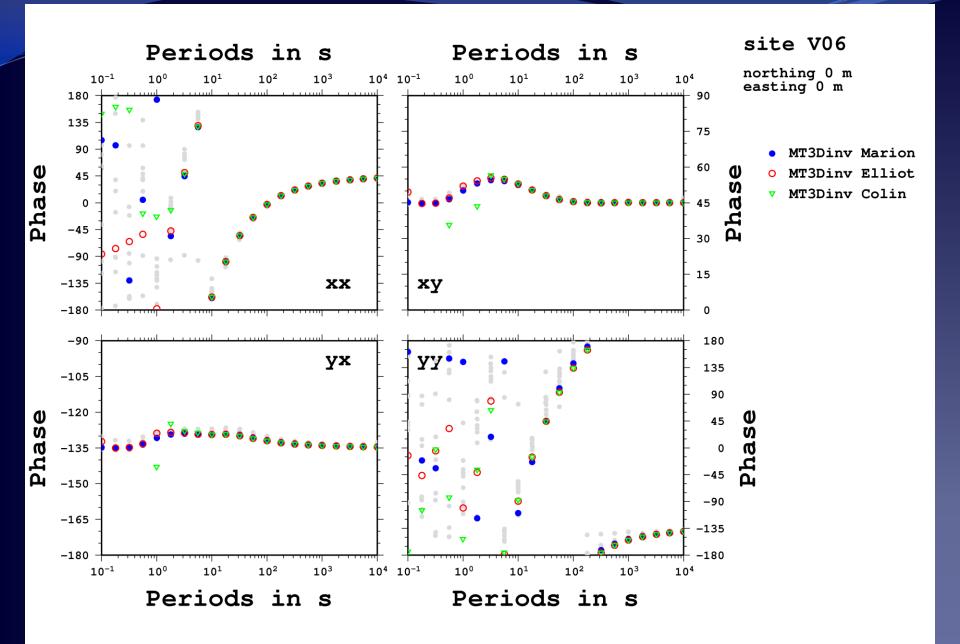


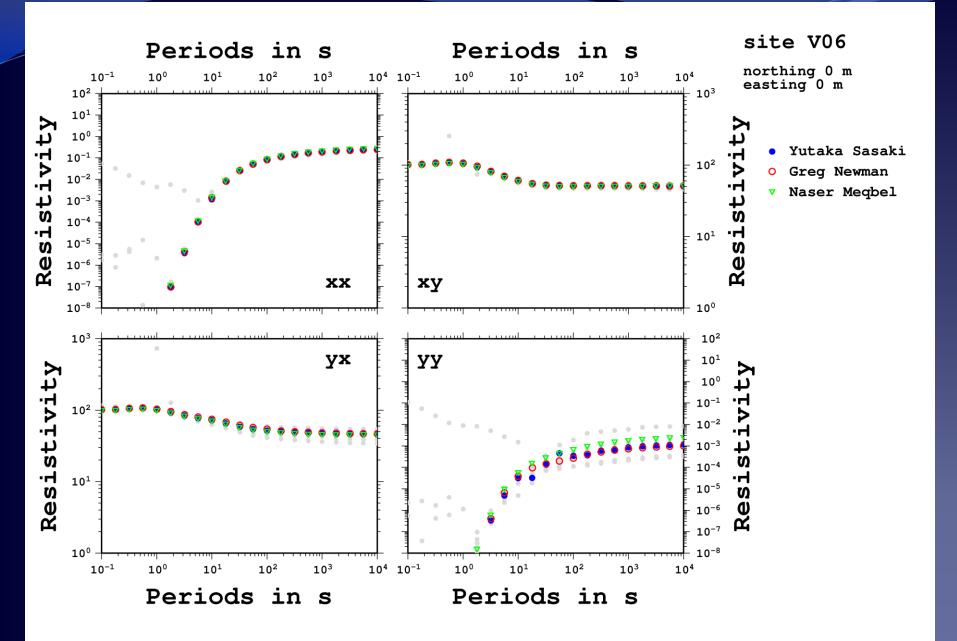
2nd Annual St. Patrick's Workshop, MT 3D inversion , 12th – 14th March 2008

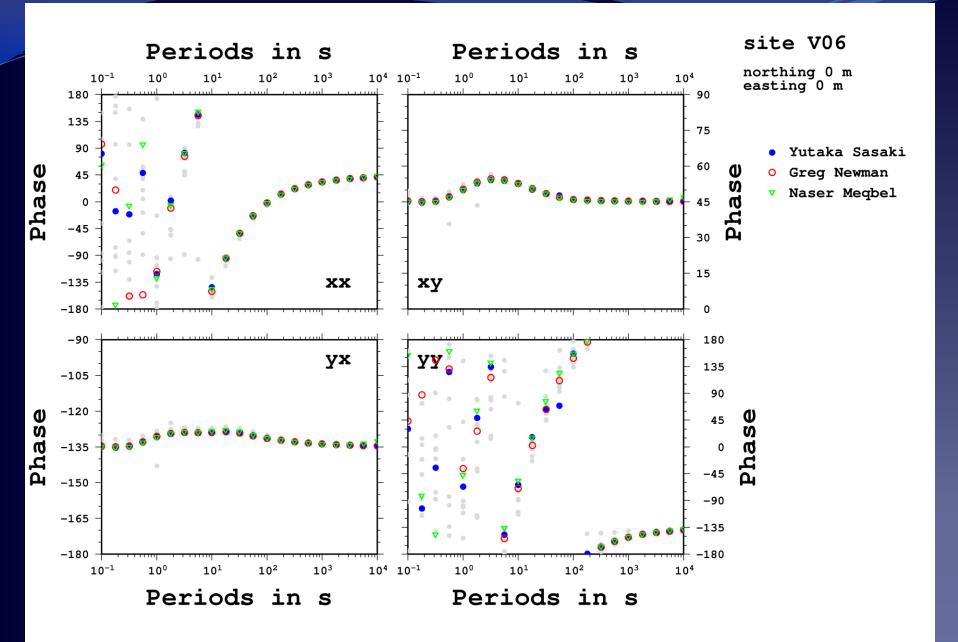


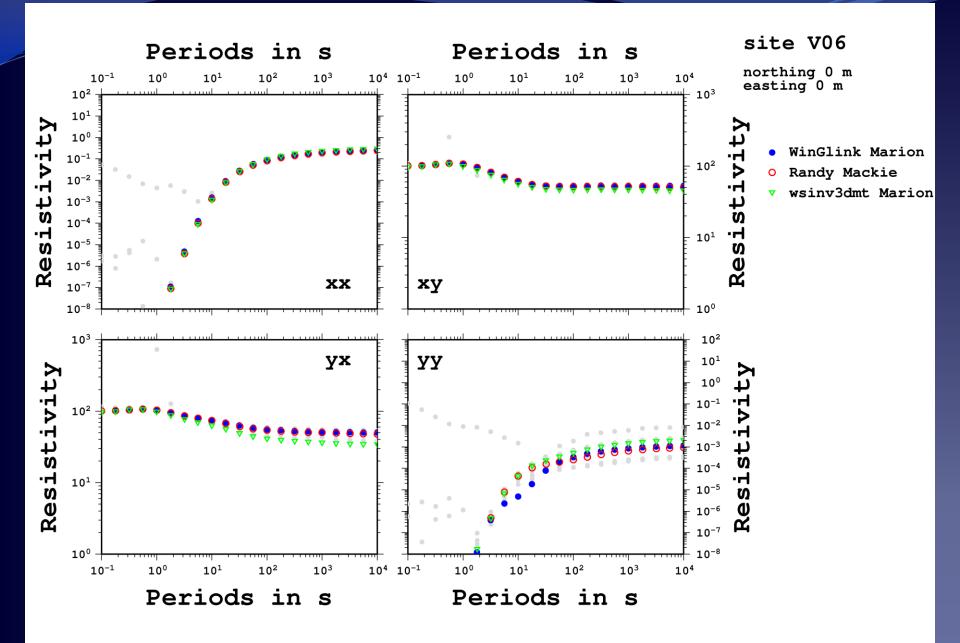


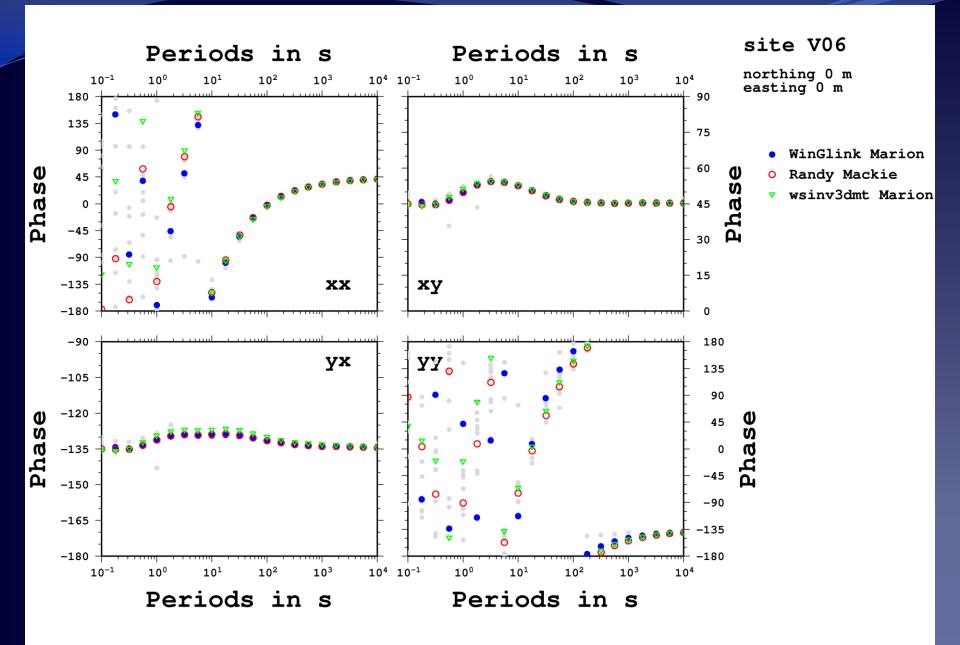


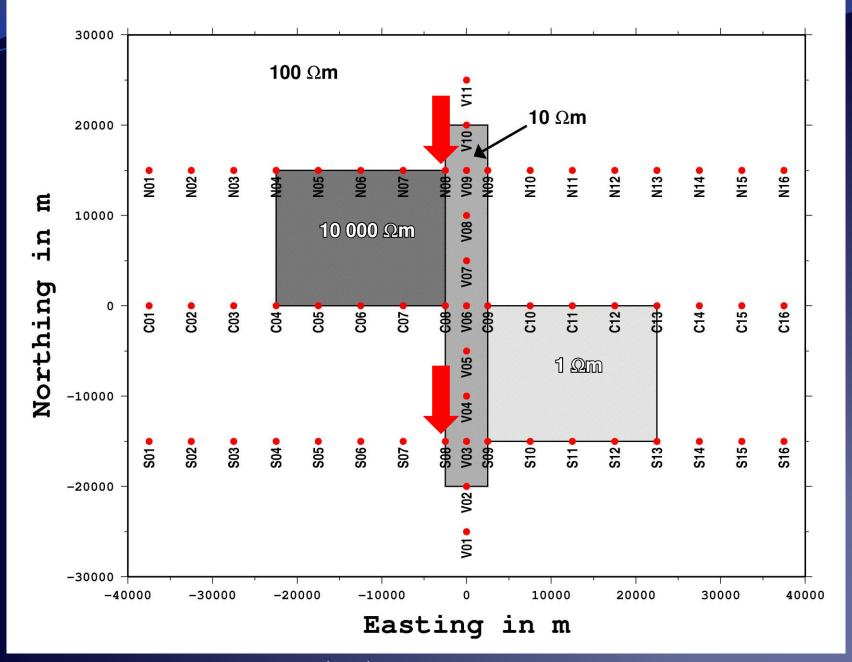


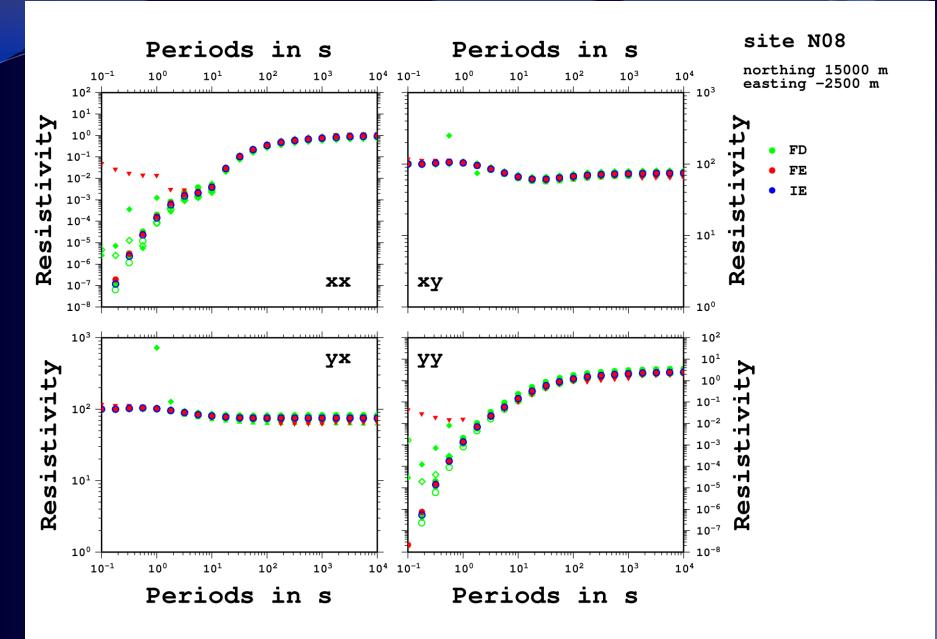


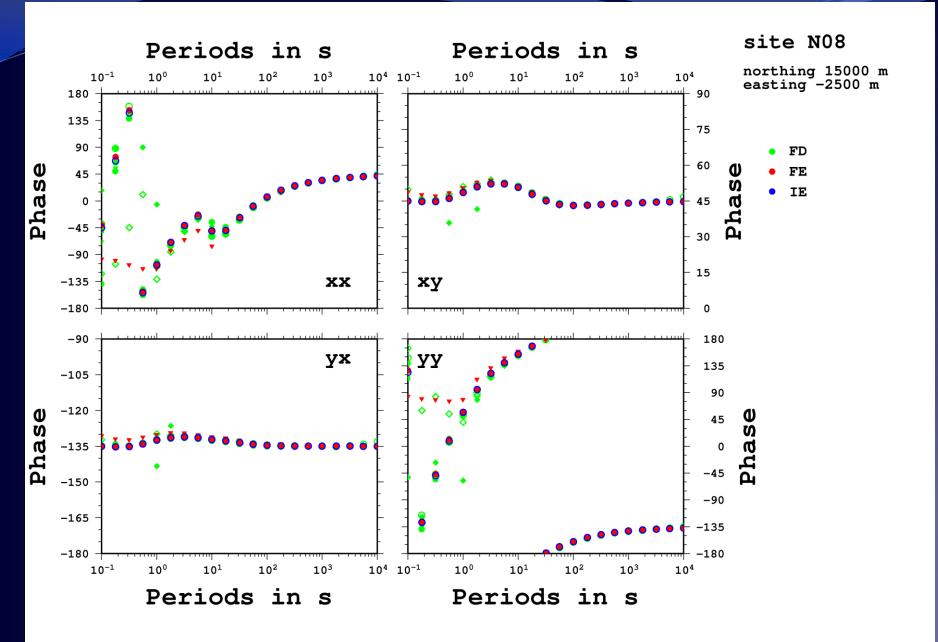


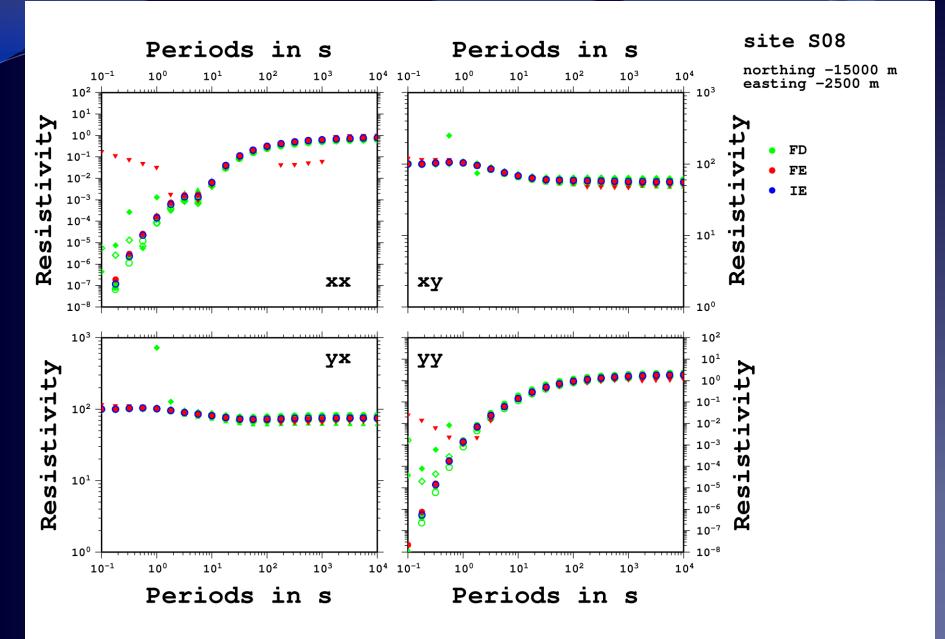


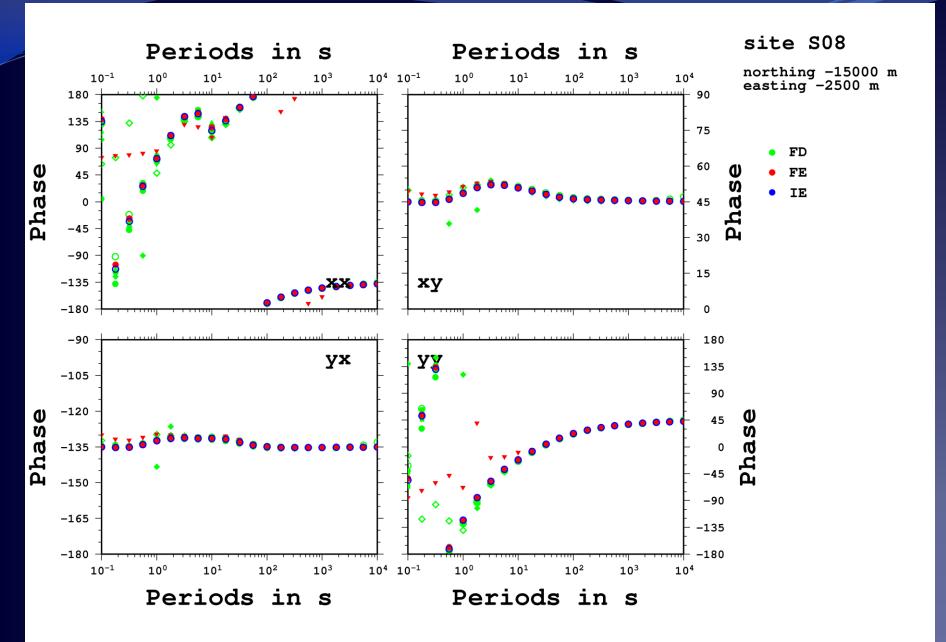












Conclusion

For comparison it is important:

- to get the sign of the time dependence correct (use same convention)
- to use the same units
- to use the same coordinate system (know what kind of rotation etc. is needed)